

KIAS Workshop, 5/Sep./2015

Anomalous Driven Motion of Biopolymers

Stretching, Compression & Rotational Dynamics

Takahiro Sakaue

Department of Physics, Kyushu University

supported by:



JSPS Core-to-Core program 2013-2015

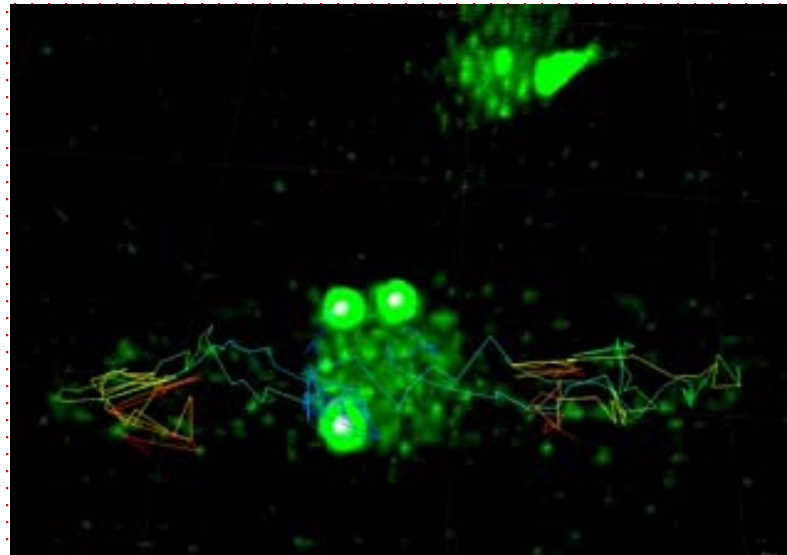
Non-equilibrium dynamics of soft matter and information



Coordinator : Shin-ichi Sasa (Department of Physics, Kyoto University)

Chromosome dynamics

M-phase (yeast cell)



Green:

cell nucleus

White:

Spindle pole body (SPB)

Telomere

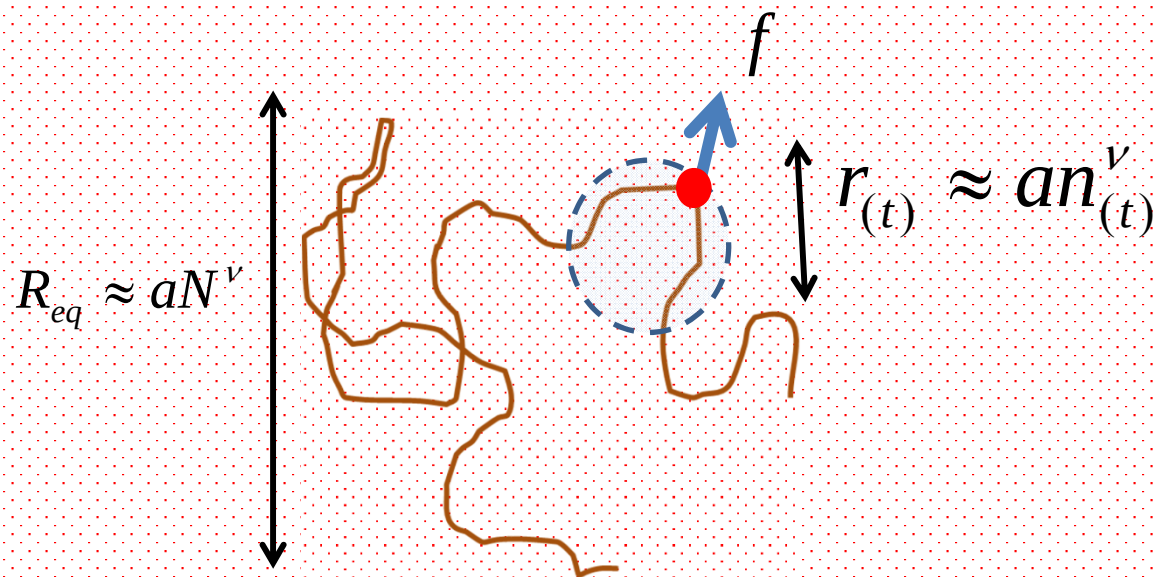


Courtesy of T. Sugawara & H. Nishimori (Hiroshima University)

Tagged monomer diffusion: A paradigm of anomalous diffusion

- Time-dependent friction (diffusion coeff.)
- Memory effect
- Visco-elastic response

Tension propagation



Rouse model

$$n(t) \sim t^{1/2}$$
$$\sim \Gamma(t) \sim 1/D(t)$$

sub-diffusion

$$\rightarrow r(t) \sim \sqrt{D(t)t} \sim t^{1/4}$$

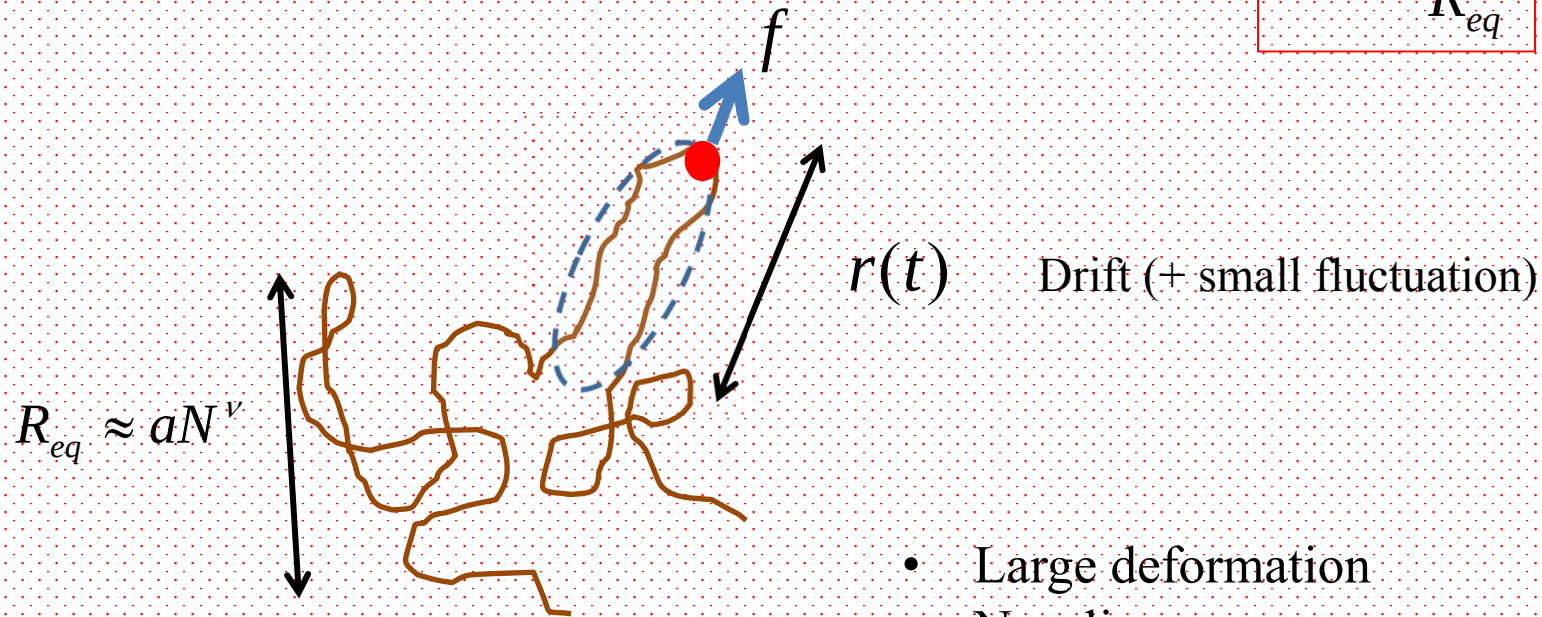
Terminal time

$$n(\tau) \sim N \Leftrightarrow r(\tau) \sim R_{eq}$$

$$\rightarrow \tau \sim N^2$$

Strong force (non-equilibrium dynamics)

$$f \gg \frac{k_B T}{R_{eq}}$$



- Large deformation
- Non-linear response
- Tension propagation

$$v(t) = \int_{-\infty}^t ds \, \underline{\mu(t-s)} f(s) + \eta(t)$$

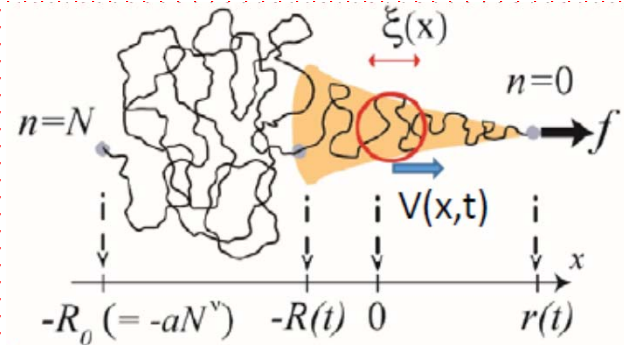
$$\int_{-\infty}^t ds \, \underline{\gamma(t-s)} v(s) = f(t) + \xi(t)$$

No-linear memory kernel

Driven dynamics of biopolymers

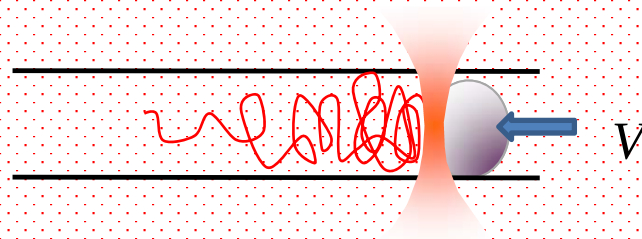
$$f > \frac{k_B T}{R_{eq}}$$

1, Stretching dynamics



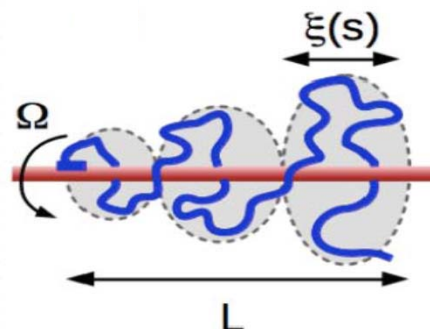
collaboration with T. Saito
(Kyoto, Japan)

2, Compression dynamics



collaboration with W. Reisner
(McGill, Canada)

3, Rotational dynamics

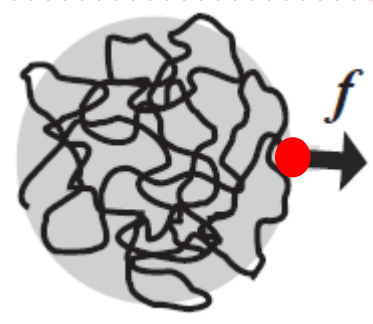


collaboration with E. Carlon
(Leuven, Belgium)

Stretching Dynamics (as a paradigm of driven dynamics)

Start pulling at $t=0$

Equilibrium (at rest)



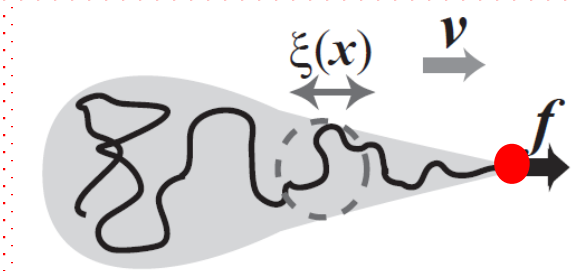
$$R_{\text{eq}} = a N^{\nu}$$



?

Transient

Steady state $t > \tau$



$$R > R_{\text{eq}}$$

Single molecule experiment, manipulation, chromosome segregation...

How to describe ?

1, Rouse model

Analytical solution

Linear (no EV, no HI)

$$\gamma \frac{\partial x_n}{\partial t} = k \frac{\partial^2 x_n}{\partial n^2} + \eta(t) + f_n(t)$$

viscous

elastic

2, Two-phase formalism

Responding and non-responding domains

Steady-state approximation for the responding domain

3, Continuum description (segment line density)

Local force balance (elastic and viscous forces)

Mass conservation

$$\longrightarrow \frac{\partial \phi(x)}{\partial t} = D_0 \frac{\partial}{\partial x} \left[\phi^{-p}(x) \frac{\partial}{\partial x} \phi(x) \right]$$

4, Non-linear Rouse model

Local force balance (elastic and viscous forces) $\frac{\partial x_n}{\partial t} = D_0 \frac{\partial}{\partial n} \left[\left(\frac{\partial x_n}{\partial n} \right)^{p-2} \frac{\partial x_n}{\partial n} \right] + \eta(t)$

T. Sakaue, T. Saito and H. Wada, Phys. Rev. E **86**, 011804 (2012).

“Dragging a polymer in a viscous fluid: Steady state and transient”

T. Saito and T. Sakaue, Phys. Rev. E **92**, 012601 (2015).

“Driven anomalous diffusion: an example from polymer stretching”

Two-phase picture

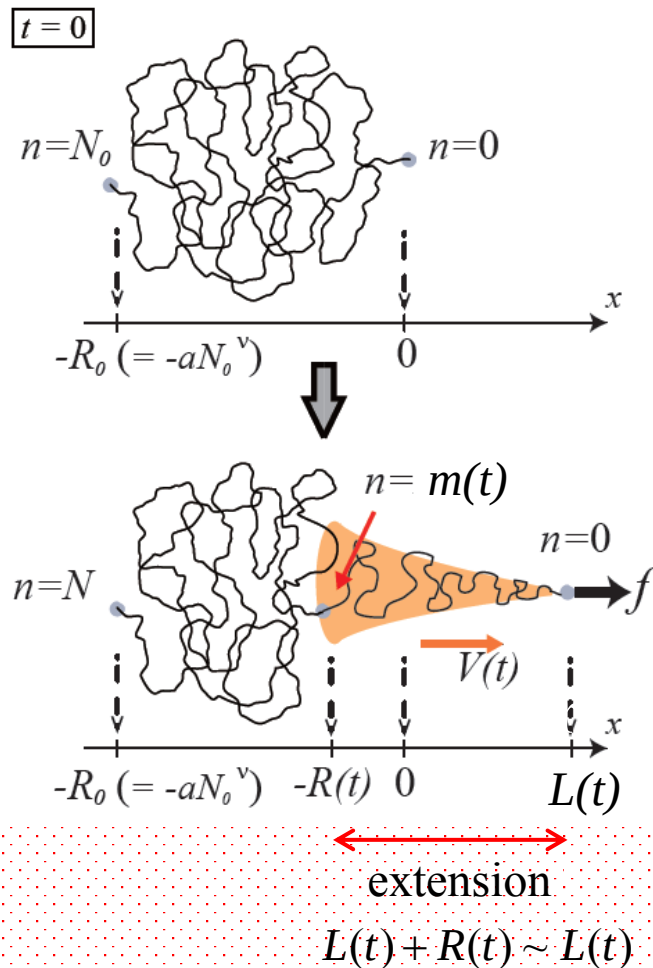
Highly non-linear, non-equilibrium process in multi-dimensional space

→ Coarse graining

Moving, and quiescent domains

Steady-state approximation
for the moving domain

Gross variables: size of the moving domain
→ front of the tension propagation



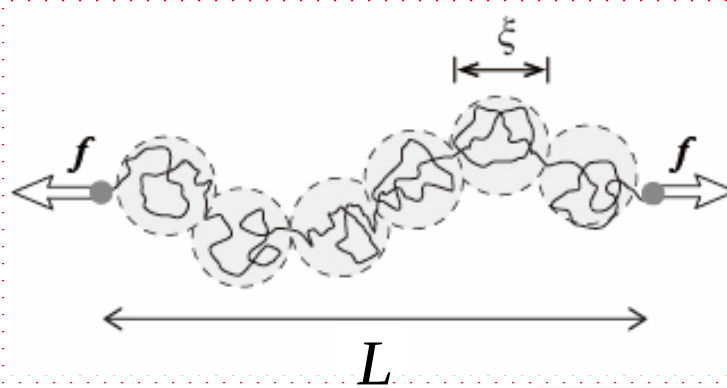
$$\Gamma(t) \frac{dL(t)}{dt} \sim f$$

$$\Gamma^{-1}(t) = \frac{\partial V(f, L)}{\partial f}$$

Steady-state
dynamical Eq. of state

Force-extension (static stretching)

Eq. of State



Alignment of blobs

$$\xi \approx k_B T / f \approx a g^\nu$$

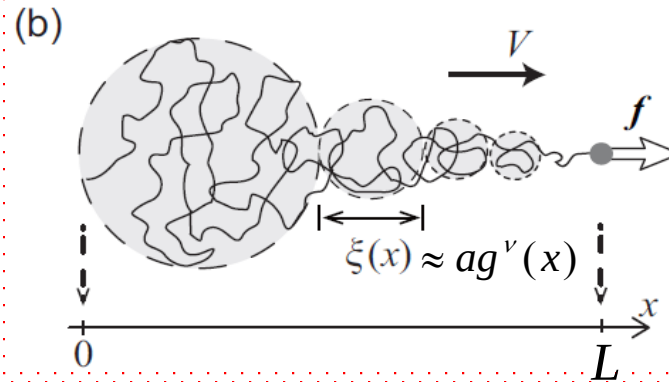
$$L \sim \xi \left(\frac{N}{g} \right) \sim N f^{(1-\nu)/\nu}$$

ν : critical exponent
(Flory)

P. Pincus (1976)

Steady State

Dynamical Eq. of State



F. Brochard-Wyart (1993)

Local force balance

$$0 = -\eta V + \frac{d}{dx} \frac{k_B T}{\xi(x)}$$

Boundary condition (f)

$$f = \frac{k_B T}{\xi(L)}$$

$$L \sim L(N, f) \quad : \text{force-extension}$$

$$V \sim V(N, f) \quad : \text{friction-law}$$

$$V \sim V(L, f)$$

Two-phase picture

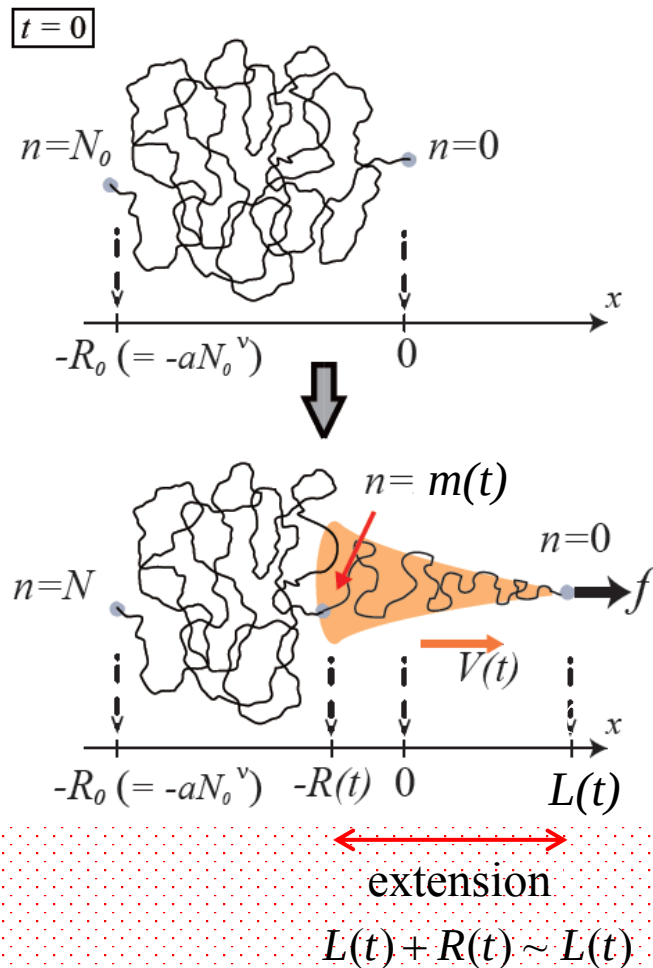
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Gross variables: size of the moving domain
→ front of the tension propagation



$$\Gamma(t) \frac{dL(t)}{dt} \sim f$$

$$\Gamma^{-1}(t) = \frac{\partial V(L, f)}{\partial f}$$

$$\left\{ \begin{array}{l} L(t) \sim f^{(z/2)-1} t^{1/2} \\ m(t) \sim f^{(z/2)-(1/\nu)} t^{1/2} \\ \tau_f \sim f^{(2/\nu)-z} N^2 \end{array} \right. \quad \text{Anomalous drift !}$$

How to describe ?

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Analytical solution

Linear (no EV, no HI)

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viscous

elastic

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$$\frac{\partial \phi(x)}{\partial t} = D_0 \frac{\partial}{\partial x} \left[\phi^{-p}(x) \frac{\partial}{\partial x} \phi(x) \right]$$

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Local force balance (elastic and viscous forces) $\frac{\partial x_n}{\partial t} = D_0 \frac{\partial}{\partial n} \left[\left(\frac{\partial x_n}{\partial n} \right)^{p-2} \frac{\partial x_n}{\partial n} \right] + \eta(t)$

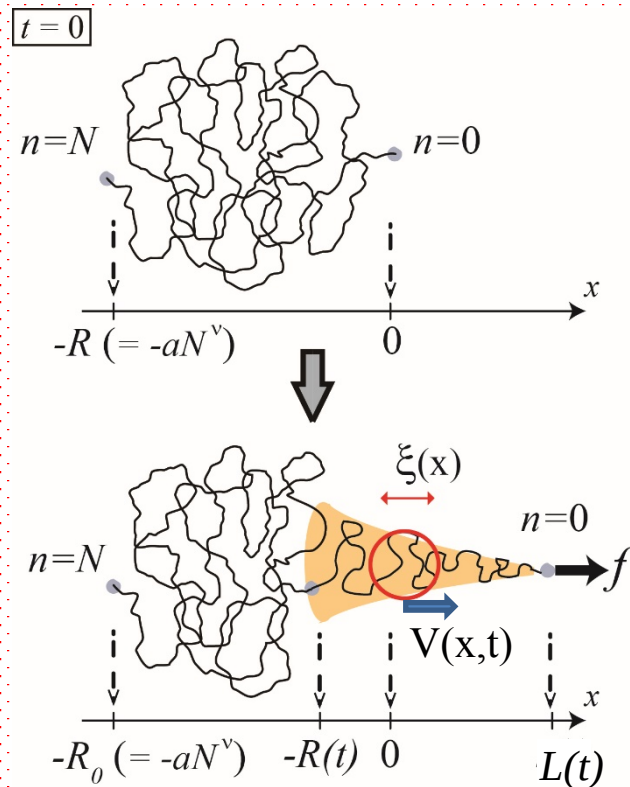
T. Sakaue, T. Saito and H. Wada, Phys. Rev. E **86**, 011804 (2012).

“Dragging a polymer in a viscous fluid: Steady state and transient”

T. Saito and T. Sakaue, Phys. Rev. E **92**, 012601 (2015).

“Driven anomalous diffusion: an example from polymer stretching”

Continuum description : porous medium equation



Local force balance

$$\eta \left(\frac{\xi(x,t)}{a} \right)^{z-3} V(x,t) = \frac{d}{dx} \frac{k_B T}{\xi(x,t)}$$

segment line density

$$\phi(x,t) = \frac{g}{\xi} \sim \xi^{(1-\nu)/\nu}$$

segment flux

$$J(x,t) = \phi(x,t)V(x,t)$$

continuity equation

$$\frac{\partial \phi(x,t)}{\partial t} = D_0 \frac{\partial}{\partial x} \left[\phi^{-p}(x,t) \frac{\partial}{\partial x} \phi(x,t) \right]$$

self-similar ansatz

$$\left(p = \frac{\nu(z-2)}{1-\nu} \right)$$

$$\longrightarrow L(t) \sim f^{(z/2)-1} t^{1/2}$$

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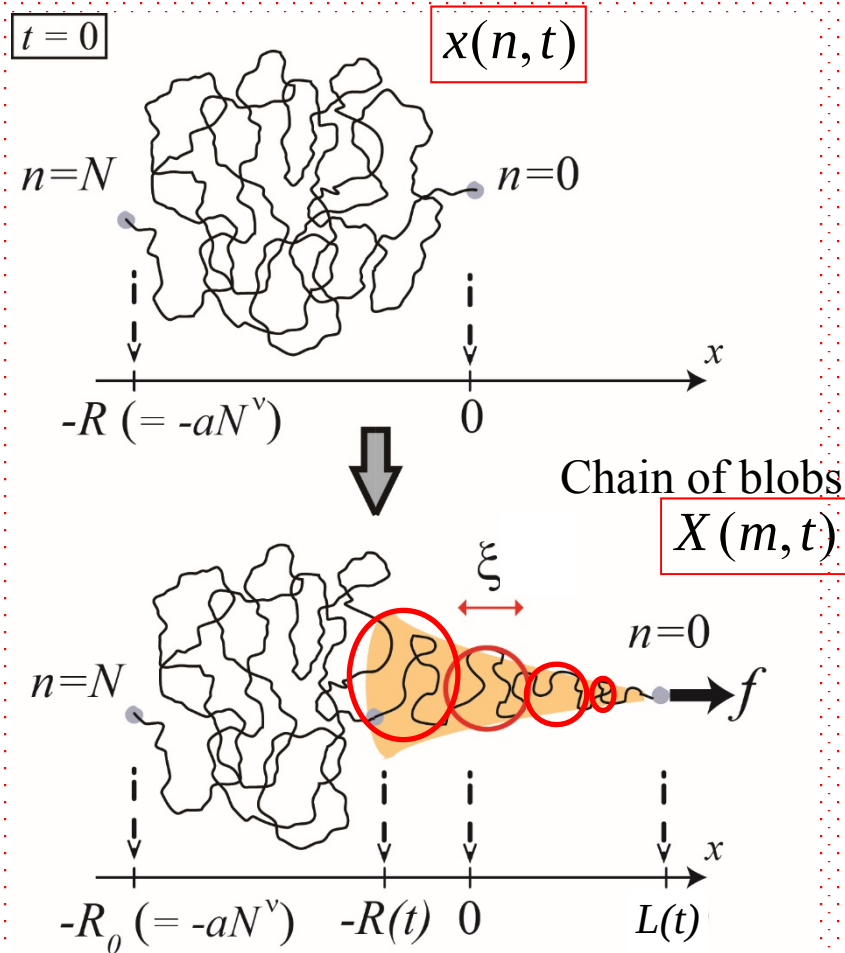
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Nonlinear Rouse model: P-Laplacian eq.



force balance (coarse-grained)

$$\eta a \left(\frac{\xi(m, t)}{a} \right)^{z-2} \frac{\partial X(m, t)}{\partial t} = \frac{\partial}{\partial m} \left(\frac{k_B T}{\xi^2(m, t)} \frac{\partial X(m, t)}{\partial m} \right)$$

$X(m, t) \rightarrow x(n, t)$: fine-graining

$$\frac{\partial x_n}{\partial t} = D_0 \frac{\partial}{\partial n} \left[\left(\frac{\partial x_n}{\partial n} \right)^{p-2} \frac{\partial x_n}{\partial n} \right] + \eta_n(t) + f_n(t)$$

$$\left(p = \frac{\nu(z-2)}{1-\nu} \right)$$

$$\nu=1/2, z=4$$

→ Rouse model

self-similar ansatz

$$\Rightarrow L(t) \sim f^{(z/2)-1} t^{1/2}$$

Fluctuations

T. Saito & T. Sakaue, Phys. Rev. E, **92**, 012601 (2015)
Driven Anomalous Diffusion: An example from polymer stretching

Anomalous drift, non-linear response

$$\langle x(t) \rangle \sim f^{(z/2)-1} t^{1/2}$$

Fluctuation of the driven monomer

$$\Delta x(t) \equiv x(t) - \langle x(t) \rangle$$

$$\frac{\partial x_n}{\partial t} = D_0 \frac{\partial}{\partial n} \left[\left(\frac{\partial x_n}{\partial n} \right)^{p-2} \frac{\partial x_n}{\partial n} \right] + \eta(t) + f_n$$

Gaussian approx.

$$\gamma^{(f)} \frac{\partial x_n}{\partial t} = k^{(f)} \frac{\partial^2 x_n}{\partial n^2} + \eta_n^{(f)}(t) + f_n$$

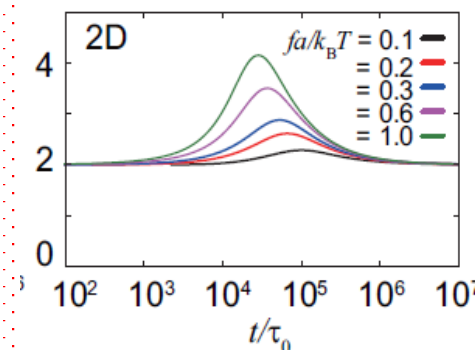
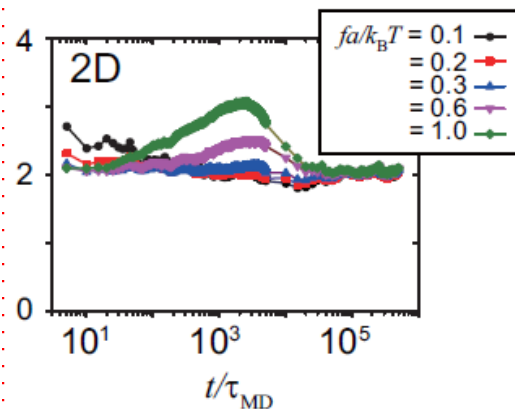
$$\langle \eta_n^{(f)}(t) \eta_m^{(f)}(s) \rangle = 2\gamma^{(f)} k_B T \delta(n-m) \delta(t-s)$$

$$k^{(f)} \sim k f^{(2\nu-1)/\nu}$$

$$\gamma^{(f)} \sim \gamma f^{2-z+(1/\nu)}$$

$$\langle \Delta x^2(t) \rangle = \frac{2k_B T}{f} \langle x(t) \rangle$$

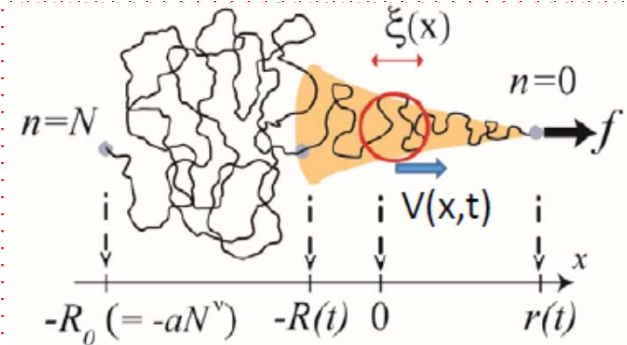
$$f \langle \Delta x^2(t) \rangle / k_B T \langle x(t) \rangle$$



Driven dynamics of biopolymers

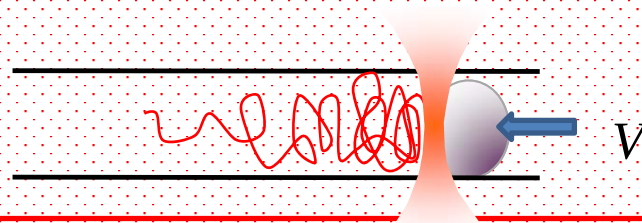
$$f > \frac{k_B T}{R_{eq}}$$

1, Stretching dynamics



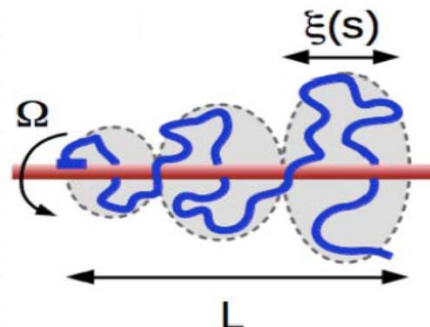
collaboration with T. Saito
(Kyoto, Japan)

2, Compression dynamics



collaboration with W. Reisner
(McGill, Canada)

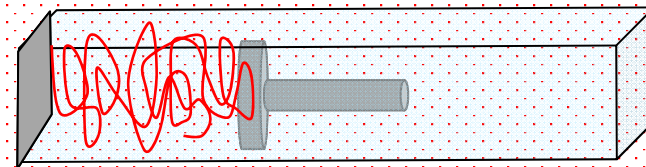
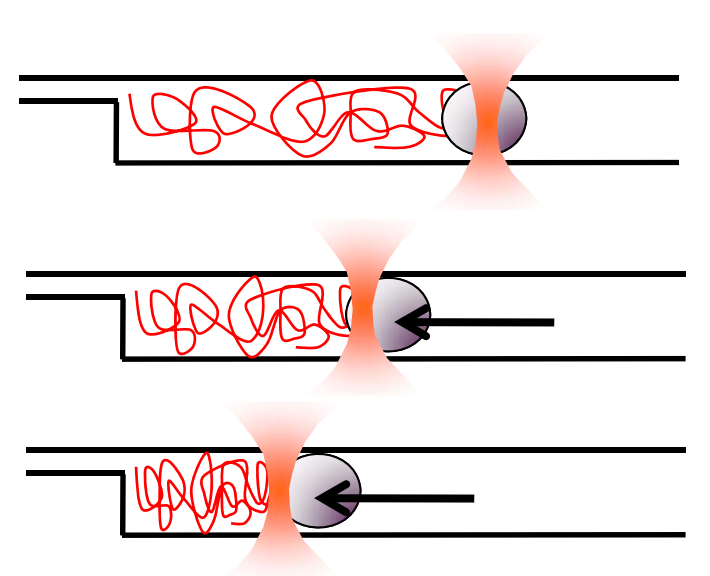
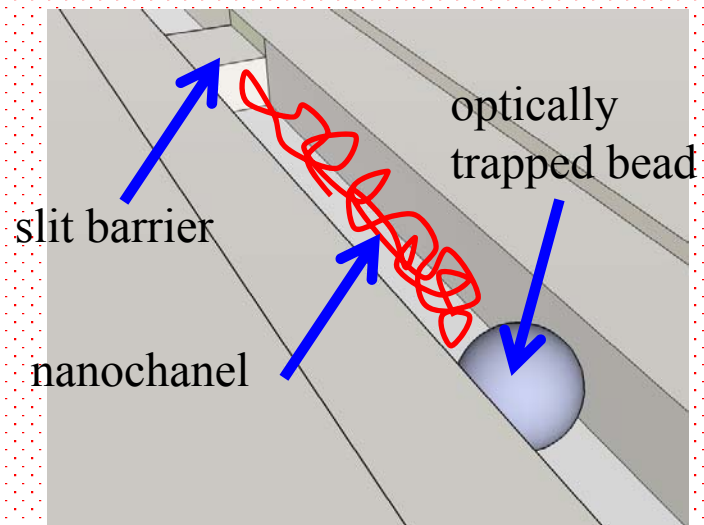
3, Rotational dynamics



collaboration with E. Carlon
(Leuven, Belgium)

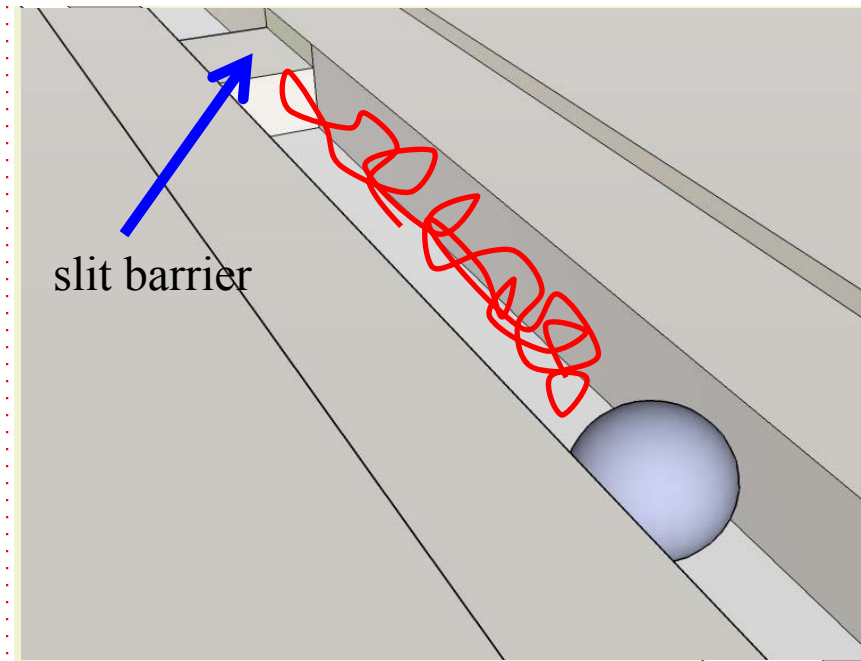
Optical Nonofluidic Piston

- Force-compression relation of confined DNA



Statics → Dynamics

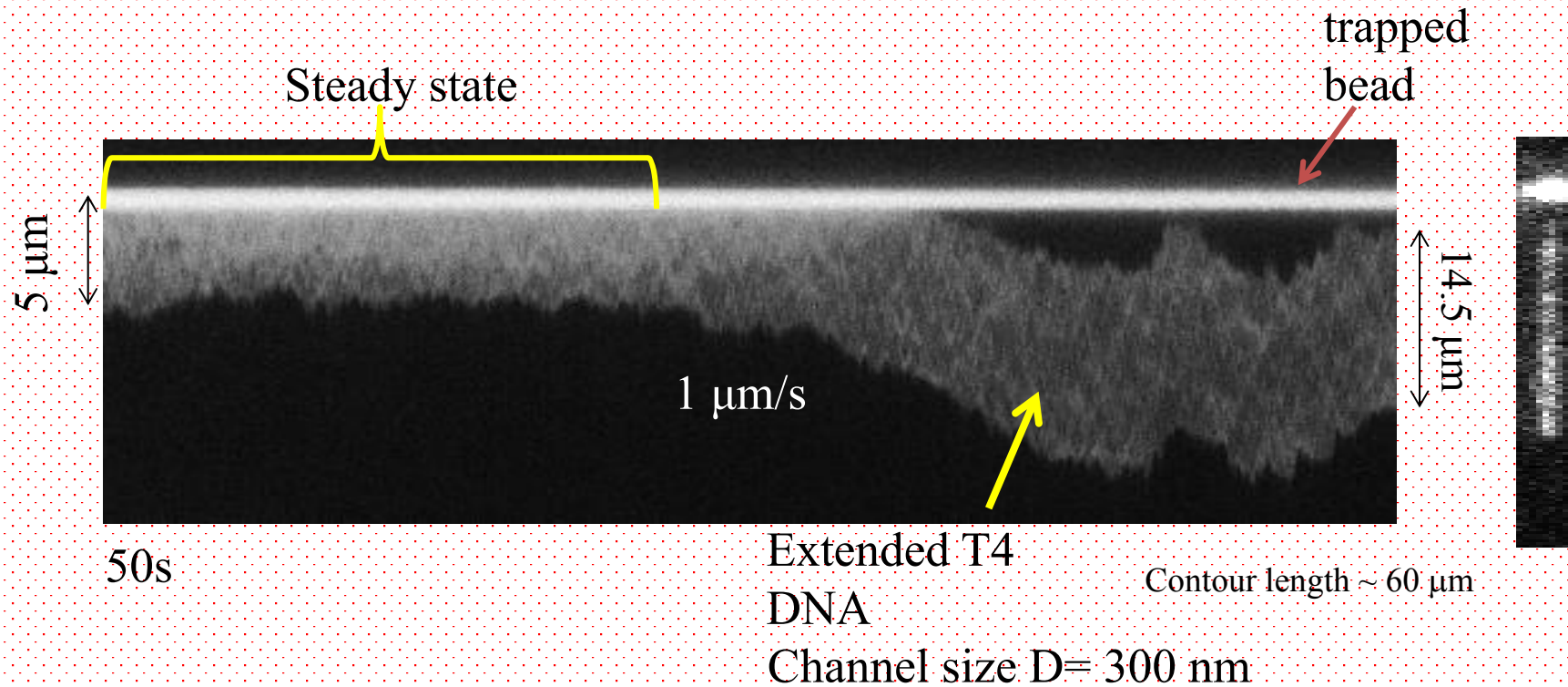
-- *no-wall pushing*



A. Khorshid, P. Zimy, D. Tetreault-La Roche, G. Massaarelli, T. Sakaue & W. Reisner
Phys. Rev. Lett., **113**, 268104 (2014)

Dynamic Compression: Raw time traces

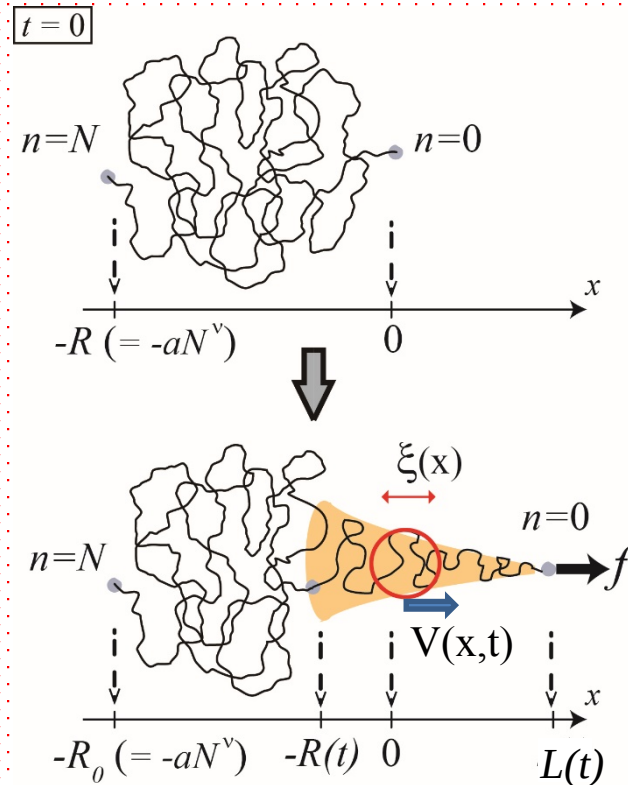
(kymograph)



- ◆ Characterization of the steady state
Control parameter: V

recall

Continuum description : porous medium equation



Local force balance

$$\eta \left(\frac{\xi(x,t)}{a} \right)^{z-3} V(x,t) = \frac{d}{dx} \frac{k_B T}{\xi(x,t)}$$

segment line density

$$\phi(x,t) = \frac{g}{\xi} \sim \xi^{(1-\nu)/\nu}$$

segment flux

$$J(x,t) = \phi(x,t)V(x,t)$$

continuity equation

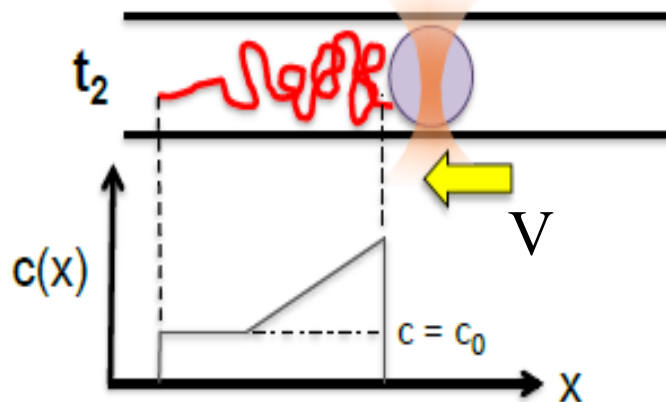
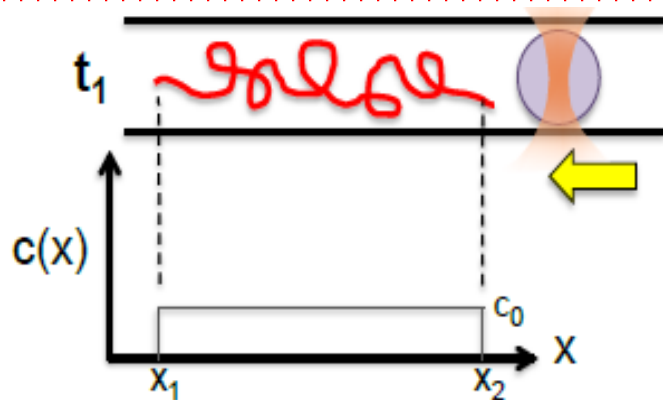
$$\frac{\partial \phi(x,t)}{\partial t} = D_0 \frac{\partial}{\partial x} \left[\phi^{-p}(x,t) \frac{\partial}{\partial x} \phi(x,t) \right]$$

self-similar ansatz

$$\left(p = \frac{\nu(z-2)}{1-\nu} \right)$$

$$\longrightarrow r(t) \sim f^{(z/2)-1} t^{1/2}$$

Continuum description : porous medium equation



Diffusive flux

Convective flux

$$\frac{\partial \phi(x, t)}{\partial t} = \frac{\partial}{\partial x} \left[D(\phi(x, t)) \frac{\partial}{\partial x} \phi(x, t) - \phi(x, t) V \right]$$

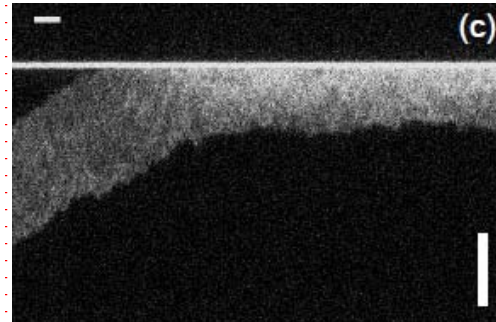
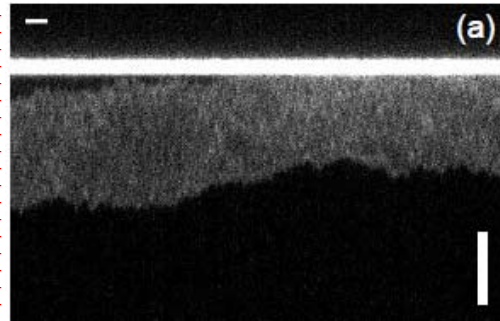
$$D(\phi) = D_0 \phi^\alpha$$

Cooperative diffusion

Steady-state: $j=0$

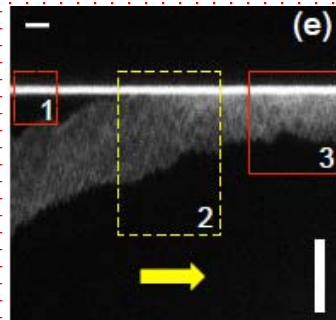
- ◆ Density profile
- ◆ Dynamical Eq. of state (f-v-r)

- $V_c < V < V^*$
initial flat profile
with ϕ_{eq}



$$V^* \approx 1.4 \mu\text{m/s}$$

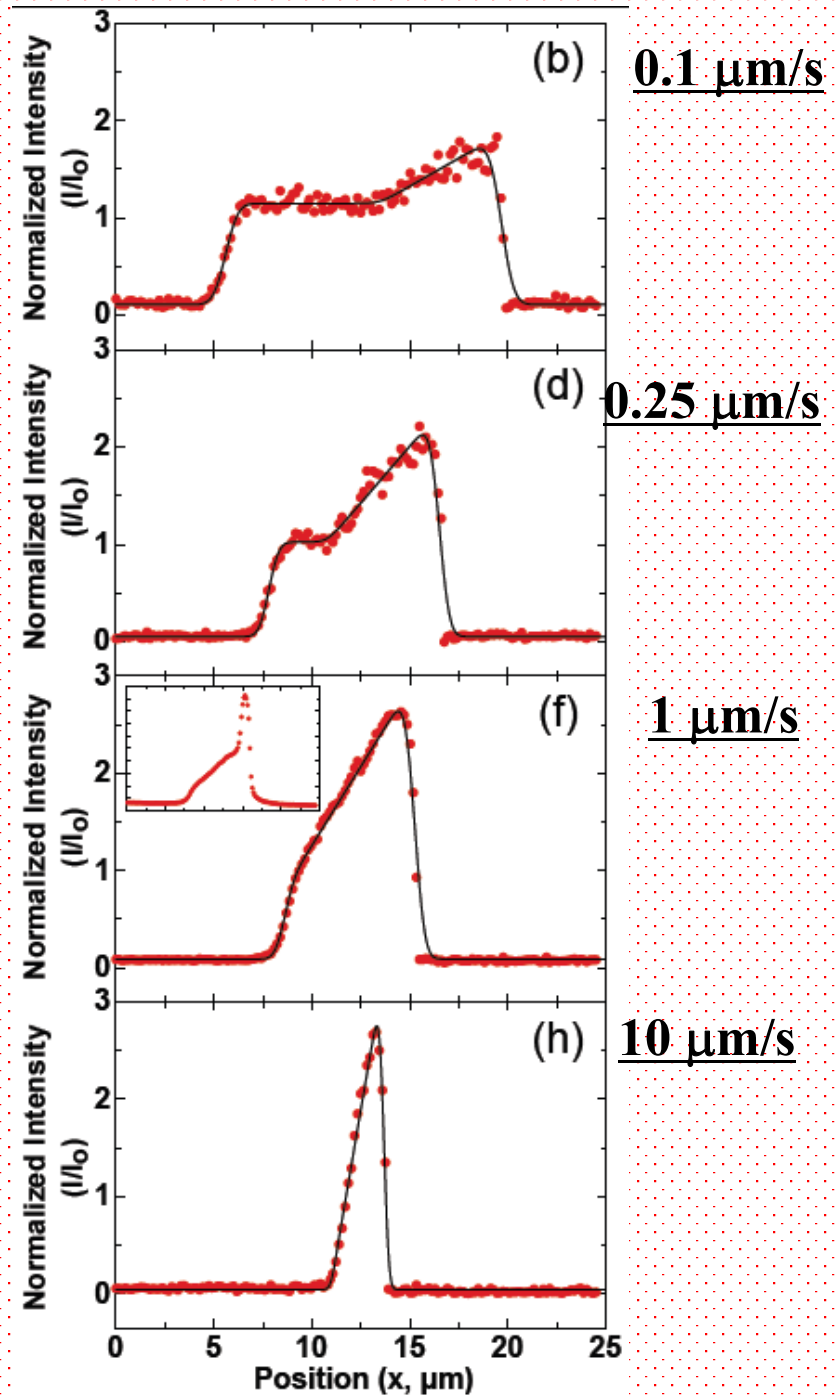
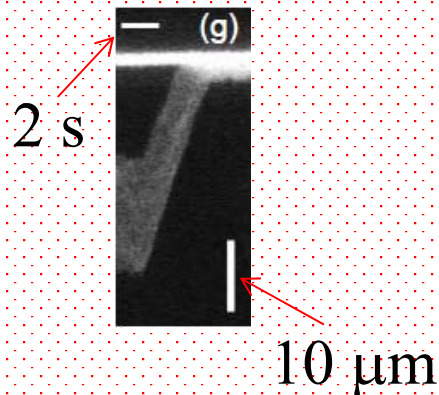
- $V > V^*$
entire chain deformed



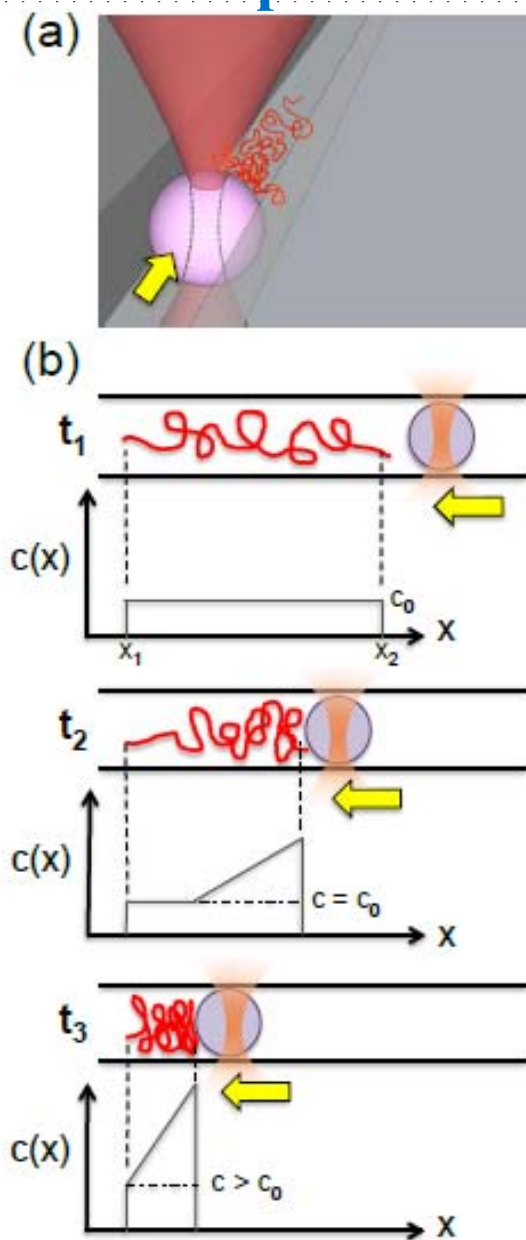
- Ramp profile

$$\phi_s(x) \sim \left(\mu \frac{x}{D} \right)^\alpha \quad (x \gg D)$$

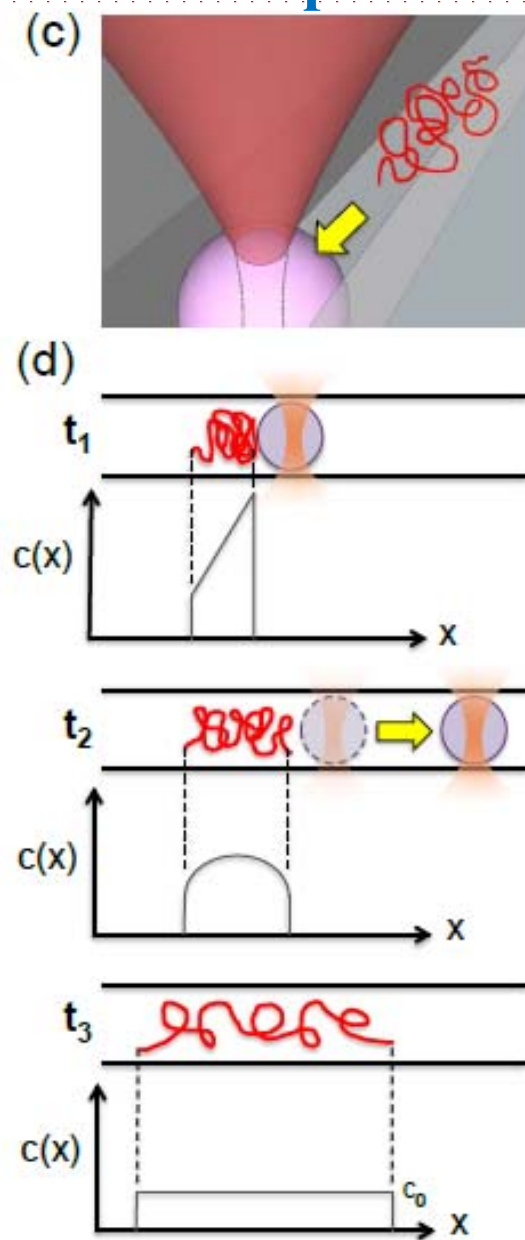
$$\alpha = 1$$



Compression



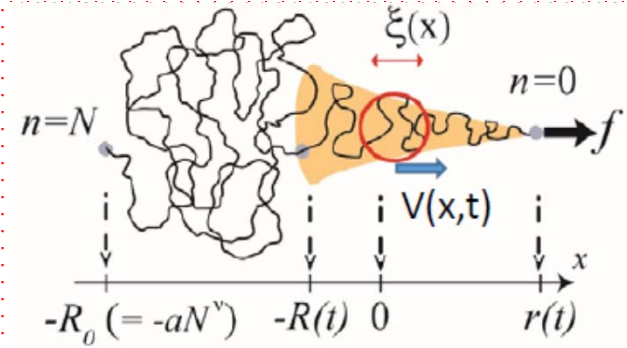
Decompression



Driven dynamics of biopolymers

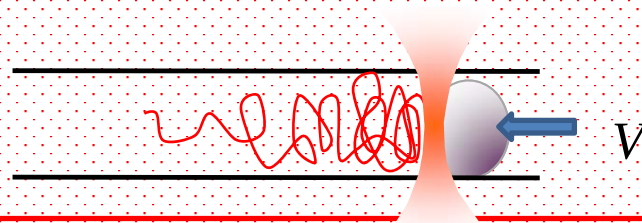
$$f > \frac{k_B T}{R_{eq}}$$

1, Stretching dynamics



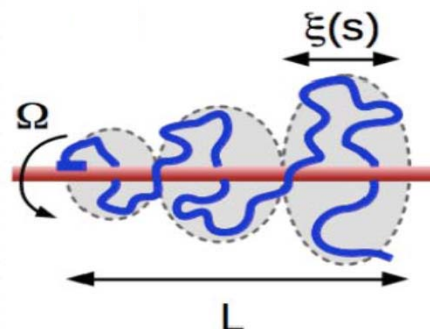
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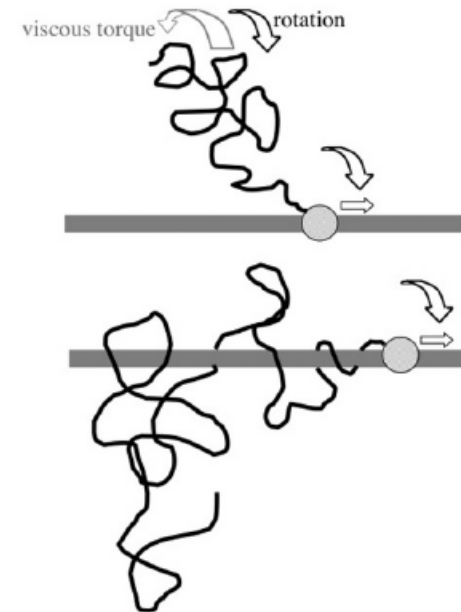
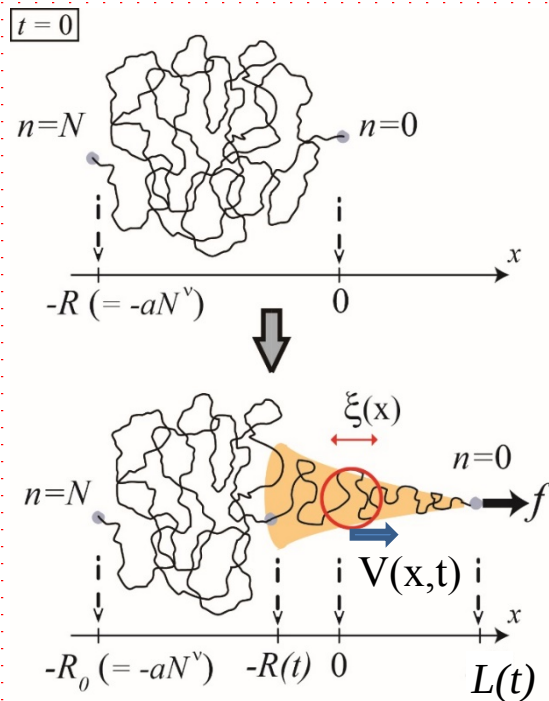
3, Rotational dynamics



collaboration with E. Carlon
(Leuven, Belgium)

“Torque-induced rotational dynamics in polymers: Torsional blobs and thinning”

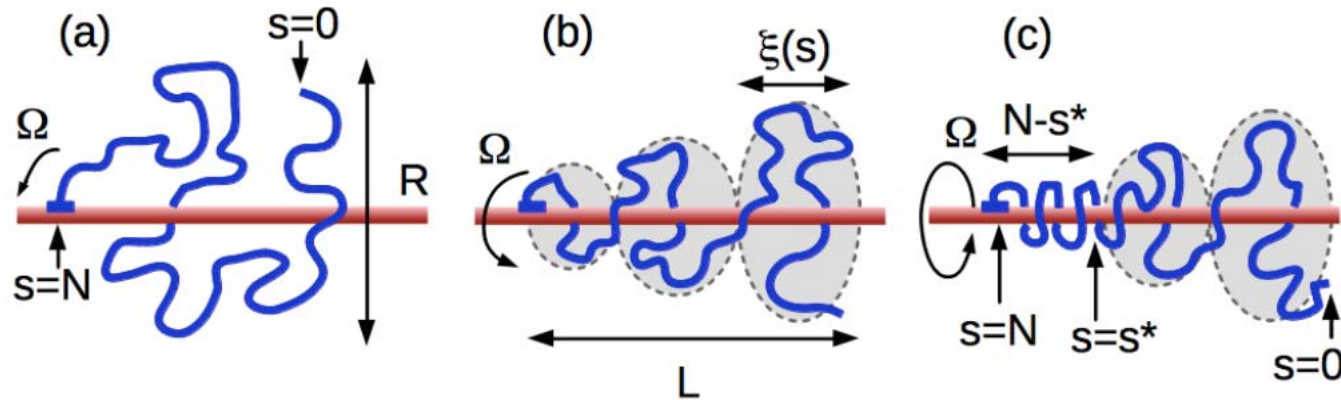
M. Laleman, M. Baiesi, B.P. Belotserkovskii, T. Sakaue, J-C. Walter, E. Carlon, *submitted*



Belotserkovskii, PRE (2014)

- ◆ Rotational analogue of the stretching dynamics
- ◆ Fundamental polymer dynamics problem
- ◆ Relevant to RNA transcription process

Steady state (driven by torque)



Torque- *torsional blob* relation

$$M(s) \approx \frac{k_B T}{[\ln(\xi(s)/a)]^\alpha}$$

cf. force-tensile blob relation $f(s) \approx \frac{k_B T}{\xi(s)}$

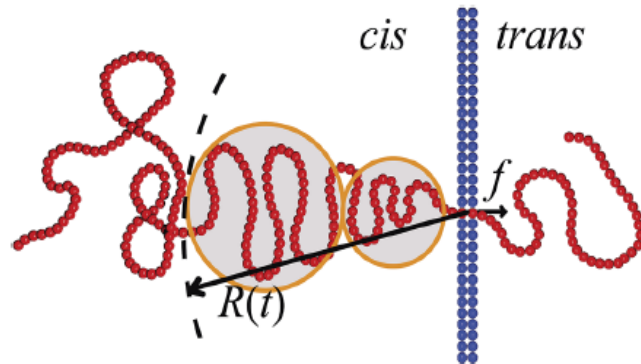
Winding angle distribution

$$P_\theta(\theta, N) = f_\theta\left(\frac{\theta}{(\ln N)^\alpha}\right)$$

- ◆ Steady state profile $\xi(s) \sim (\Omega s)^{-1/2}$
- ◆ Torque-angular velocity relation (dynamical eq. of state)
- ◆ Steady elongation

Summary: Driven dynamics of biopolymers

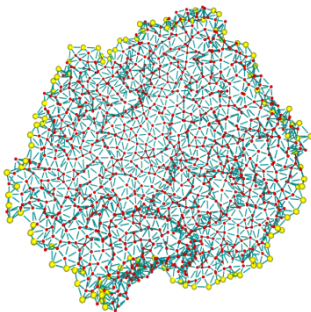
Translocation



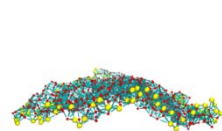
Palyulin et. al, SoftMatter (2014)

Polymerized membrane

(top)

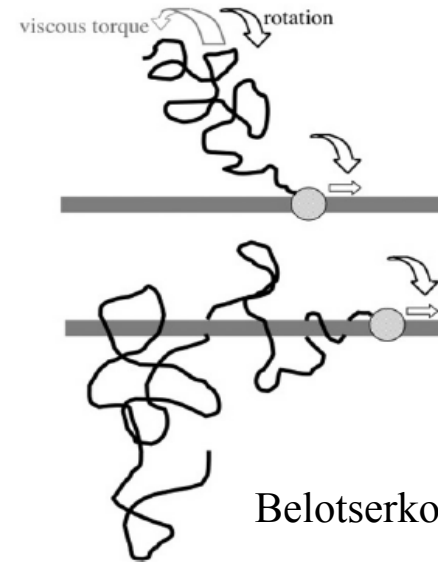


(side)



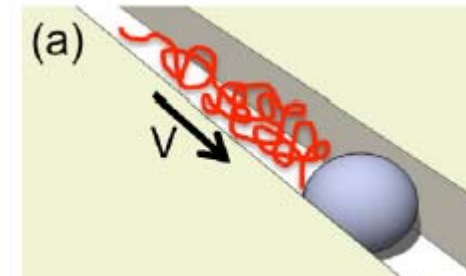
Mizuochi, Nakanishi, Sakaue, EPL (2014)

Transcription



Belotserkovskii, PRE (2014)

Confined DNA (Nanodozer)



Khorshid, Sakaue, Reisner et. al., PRL (2014)

Acknowledgements:

T. Saito (Kyoto), W. Reisner (McGill), E. Carlon (Leuven)

T. Sugawara, H. Nishimori (Hiroshima)