

Neural Islands: An analytical model of the late stage of reionization

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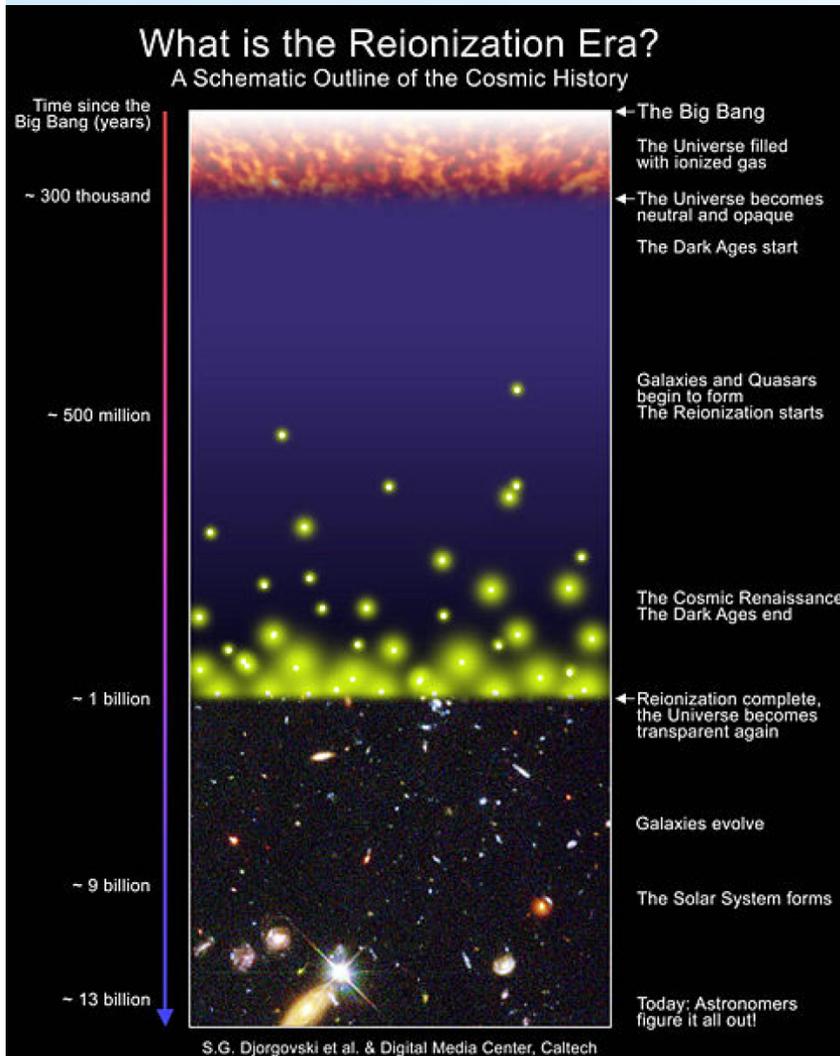
National Astronomical Observatory,
Chinese Academy of Sciences

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Based on Yidong Xu, Bin Yue, Meng Su, Zuhui Fan, Xuelel Chen:

ApJ 781, 97 (2014)

Epoch of Reionization



Current Observational Probes

CMB polarization → $z \sim 11$;

Gunn-Peterson tests → complete at $z \sim 6$;

Deep Field high- z galaxies

Upcoming & Future:

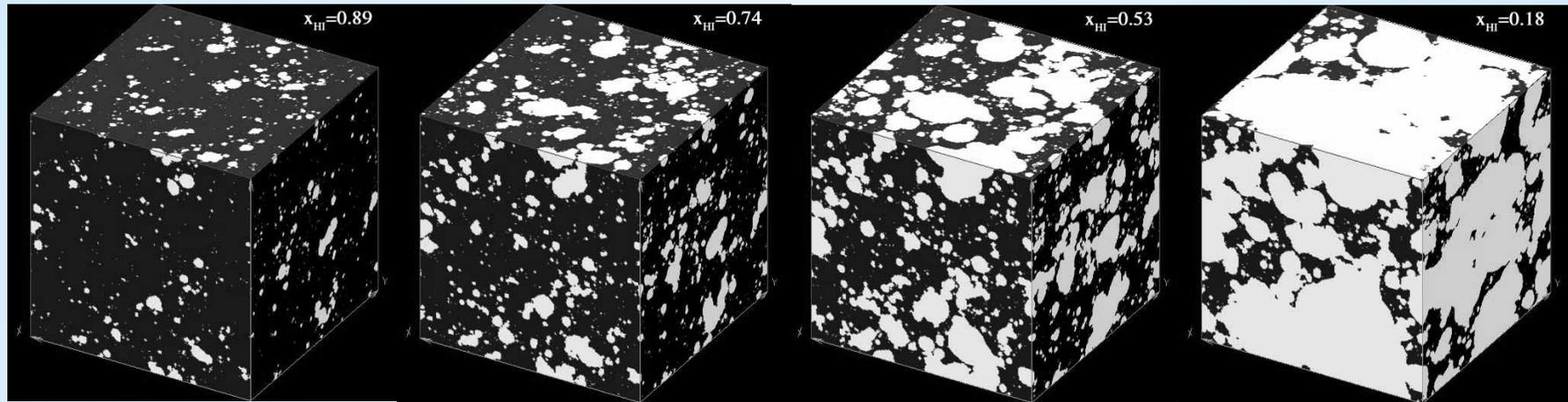
21cm experiments

EDGES, 21CMA, LOFAR< PAPER, LWA, MWA,

LOFAR, HERA, SKA

high- z galaxy observations: JWST, ...

Theoretical Understanding



(From Mesinger & Furlanetto 2007 ApJ, 669, 663)

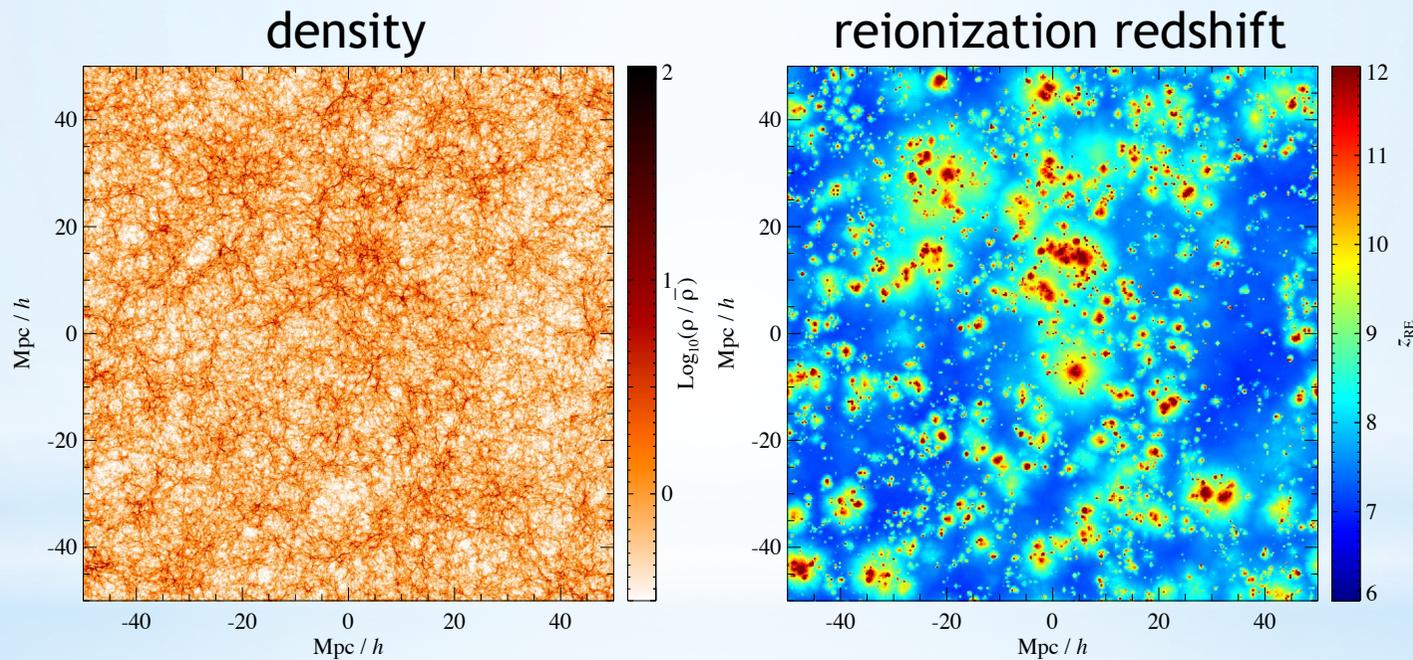
- formation of first stars
- feedback
- formation of first galaxies and blackholes
- subsequent galaxy formation
- radiative transfer

Tools of Investigation:

- Numerical Simulations
- Analytical Model
bubble model (Furlanetto et al 2004)
- Semi-Numerical Model

Basis of Analytical Model

The reionization field follows the density field on large scales



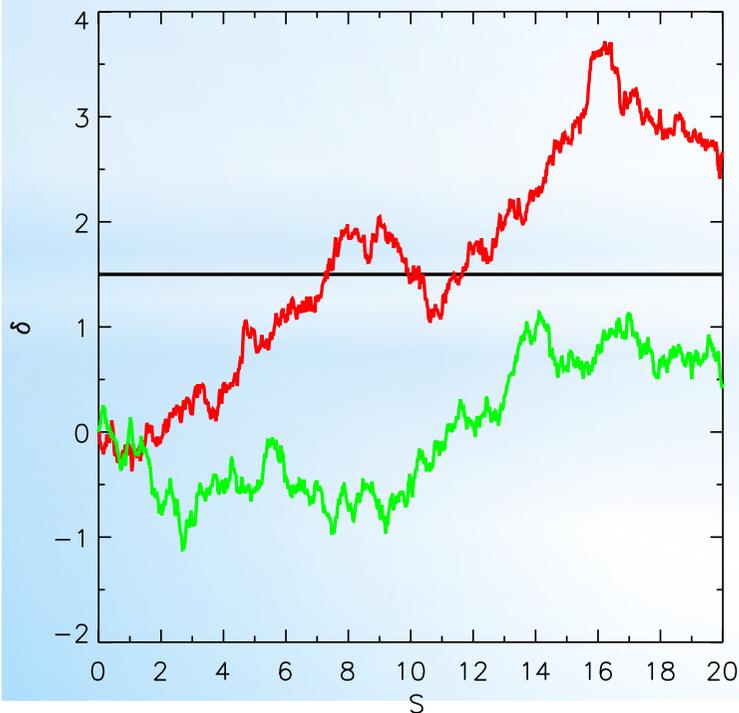
(From Battaglia et al. 2013 ApJ, 776, 81)

Modeling structure growth and halo formation: Excursion Set Theory

(Bond et al. 1991, Lacey & Cole 1993)

The linearly extrapolated density contrast field $\delta(x, R)$, $S = \sigma^2(R)$
k-space top-hat window function

- Each trajectory of $\delta(S)$ executes a random walk, halo identified when up crossing a preset barrier
- To solve the *cloud-in-cloud* problem, **first** up-crossing distribution



$$\Pi(\delta, S + \Delta S) = \int d(\Delta\delta) \Psi(\Delta\delta; \Delta S) \Pi(\delta - \Delta\delta, S).$$

$$\Psi(\Delta\delta; \Delta S) d(\Delta\delta) = \frac{1}{\sqrt{2\pi\Delta S}} \exp\left(-\frac{(\Delta\delta)^2}{2(\Delta S)^2}\right) d(\Delta\delta)$$

$$\frac{\partial \Pi}{\partial S} = \frac{1}{2} \frac{\partial^2 \Pi}{\partial \delta^2}$$

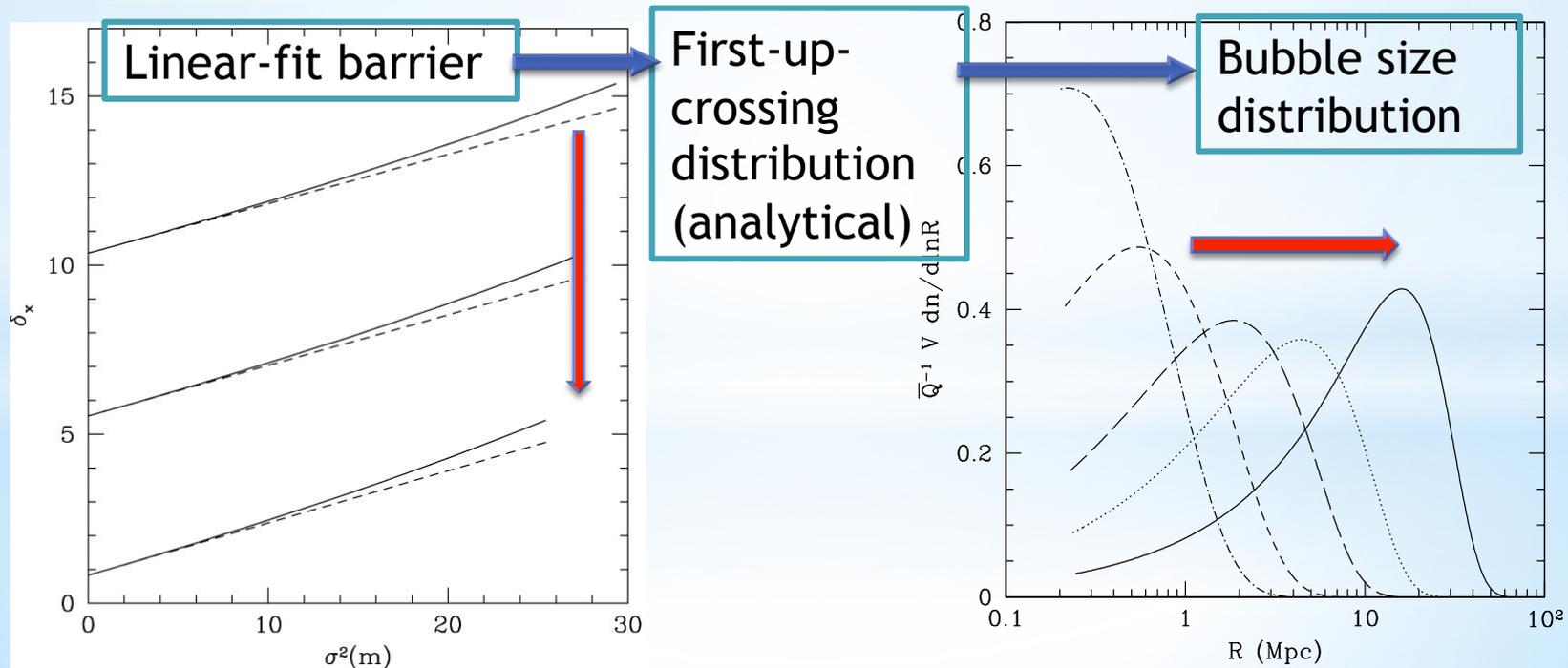
$$\Pi(\delta, S) = \frac{1}{\sqrt{2\pi\Delta S}} \left[\exp\left(-\frac{(\Delta\delta)^2}{2\Delta S}\right) - \exp\left(-\frac{[2(\delta_c - \delta_0) - \Delta\delta]^2}{2\Delta S}\right) \right],$$

The Excursion Set Approach for ionized bubbles - The bubble model of reionization

(Furlanetto et al. 2004)

- * Relate the ionization field to the initial density field
- * Ask whether an isolated region of mass M can be fully self-ionized.

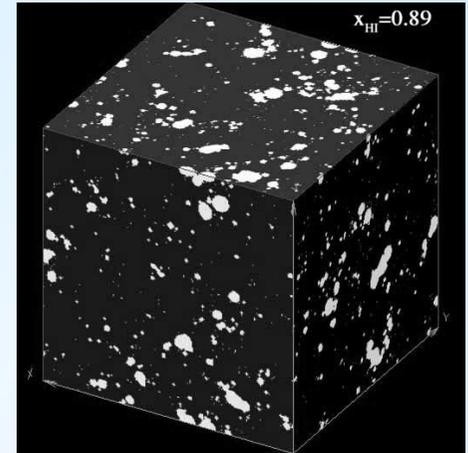
$$f_{\text{coll}} \geq f_x \equiv \zeta^{-1} \longrightarrow \delta_m \geq \delta_x(m, z) \equiv \delta_c(z) - \sqrt{2}K(\zeta)[\sigma_{\text{min}}^2 - \sigma^2(m)]^{1/2}$$



However, after percolation of bubbles...

Late Stage of EoR is interesting, and it may be easier for the upcoming instruments to probe the signal at the late reionization stages.

early



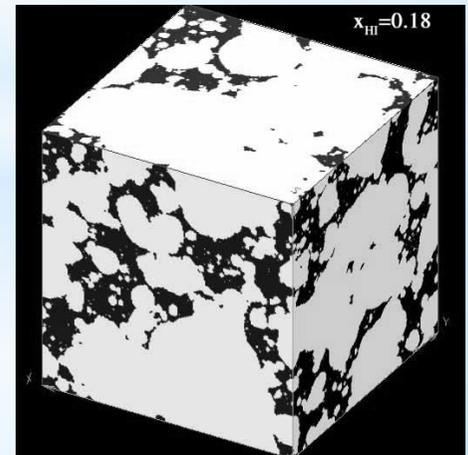
But: The isolated and spherical assumption for the ionized bubbles breaks down

→ the neutral islands are more isolated

2. The existence of an ionizing background

→ the shape of barriers could be changed

late



The island model

Note: By islands we mean large, uncollapsed regions, the minihalos and galaxies are smaller neutral regions

The Island Model

- * Negative island barrier (“inside-out” reionization)
- * Island mass scales are identified by *first-down-crossings* through the island barrier (but not the “never-up-crossing” distribution).
- * With the inclusion of an ionizing background, the condition of keeping from being ionized:

$$\xi f_{\text{coll}}(\delta_M; M, z) + \frac{\Omega_m}{\Omega_b} \frac{N_{\text{back}} m_H}{M X_H (1 + \bar{n}_{\text{rec}})} < 1,$$

→ The island barrier:

$$\delta_M < \delta_I(M, z) \equiv \delta_c(z) - \sqrt{2[S_{\text{max}} - S(M)]} \operatorname{erfc}^{-1} [K(M, z)],$$

$$K(M, z) = \xi^{-1} \left[1 - N_{\text{back}} (1 + \bar{n}_{\text{rec}})^{-1} \frac{m_H}{M (\Omega_b / \Omega_m) X_H} \right].$$

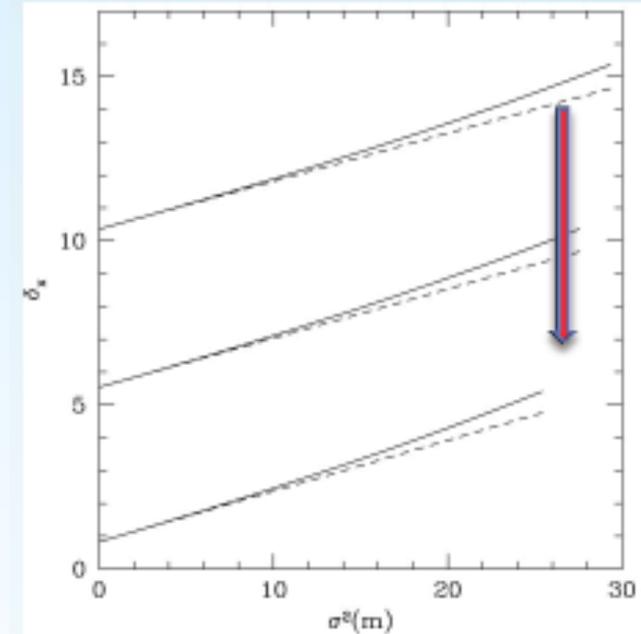
the integral number of background ionizing photons consumed by an island during the time interval between the setup of an ionizing background and the redshift under consideration.

The Island Model

* Define the “**background onset time**” as the time at which the barrier curve passes through the origin point on the $\delta - S$ plane

$$\delta_I(S = 0; z = z_{\text{back}}) = \delta_c(z_{\text{back}}) - \sqrt{2 S_{\text{max}}(z_{\text{back}})} \operatorname{erfc}^{-1}(\xi^{-1}) = 0.$$

* We take $\{f_{\text{esc}}, f_{\star}, N_{\gamma/\text{H}}, \bar{n}_{\text{rec}}\} = \{0.2, 0.1, 4000, 1\}$ as the fiducial set of parameters, so that $\xi = 40$ and $z_{\text{back}} = 8.6$.



- * Solving for the first-down-crossing distribution (Zhang & Hui 2006):
(the “island-in-island” problem is naturally solved)

$$f_I(S_I) = -g_1(S_I) - \int_0^{S_I} dS' f_I(S') [g_2(S_I, S')],$$

$$g_1(S_I) = \left[\frac{\delta_I(S_I)}{S_I} - 2 \frac{d\delta_I}{dS_I} \right] P_0[\delta_I(S_I), S_I], \quad P_0(\delta, S) = \frac{1}{\sqrt{2\pi S}} \exp\left(-\frac{\delta^2}{2S}\right)$$

$$g_2(S_I, S') = \left[2 \frac{d\delta_I}{dS_I} - \frac{\delta_I(S_I) - \delta_I(S')}{S_I - S'} \right] P_0[\delta_I(S_I) - \delta_I(S'), S_I - S'],$$

- * The mass function of islands:

$$\frac{dn}{d \ln M_I}(M_I, z) = \bar{\rho}_{m,0} f_I(S_I, z) \left| \frac{dS_I}{dM_I} \right|.$$

- * The volume fraction of neutral regions:

$$\mathbf{Q}_V^I = \int dM_I \frac{dn}{dM_I} V(M_I).$$

A toy model - island-V

- The ionizing photons permeated through the neutral islands with a uniform density (e.g. all X-rays)
 - Extremely large mean free path
 - Neglecting the absorption by dense clumps
- The averaged number density of the background ionizing photons

$$n_\gamma = \bar{n}_H f_{\text{coll}}(z) f_\star N_{\gamma/\text{H}} f_{\text{esc}} - (1 - Q_V^{\text{I}}) \bar{n}_H (1 + \bar{n}_{\text{rec}}),$$

A toy model - island-V

$$\delta_M < \delta_I(M, z) \equiv \delta_c(z) - \sqrt{2[S_{\max} - S(M)]} \operatorname{erfc}^{-1} [K(M, z)],$$

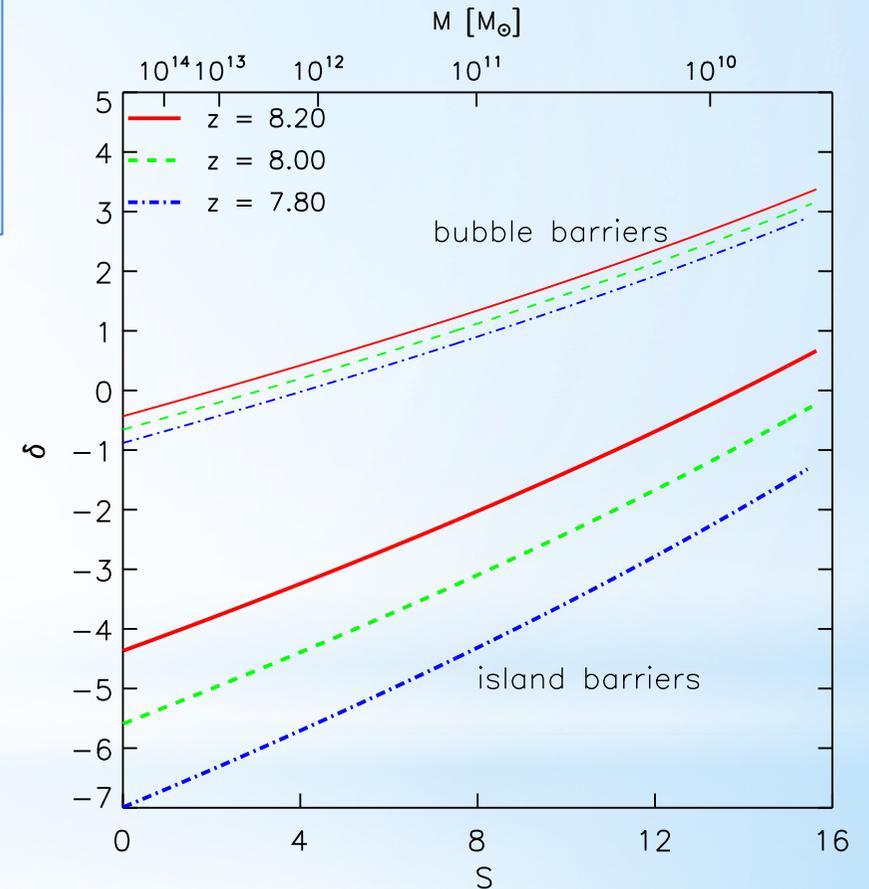
$$K(M, z) = \xi^{-1} \left[1 - N_{\text{back}} (1 + \bar{n}_{\text{rec}})^{-1} \frac{m_{\text{H}}}{M (\Omega_b / \Omega_m) X_{\text{H}}} \right].$$

➤ N_{back} proportional to V

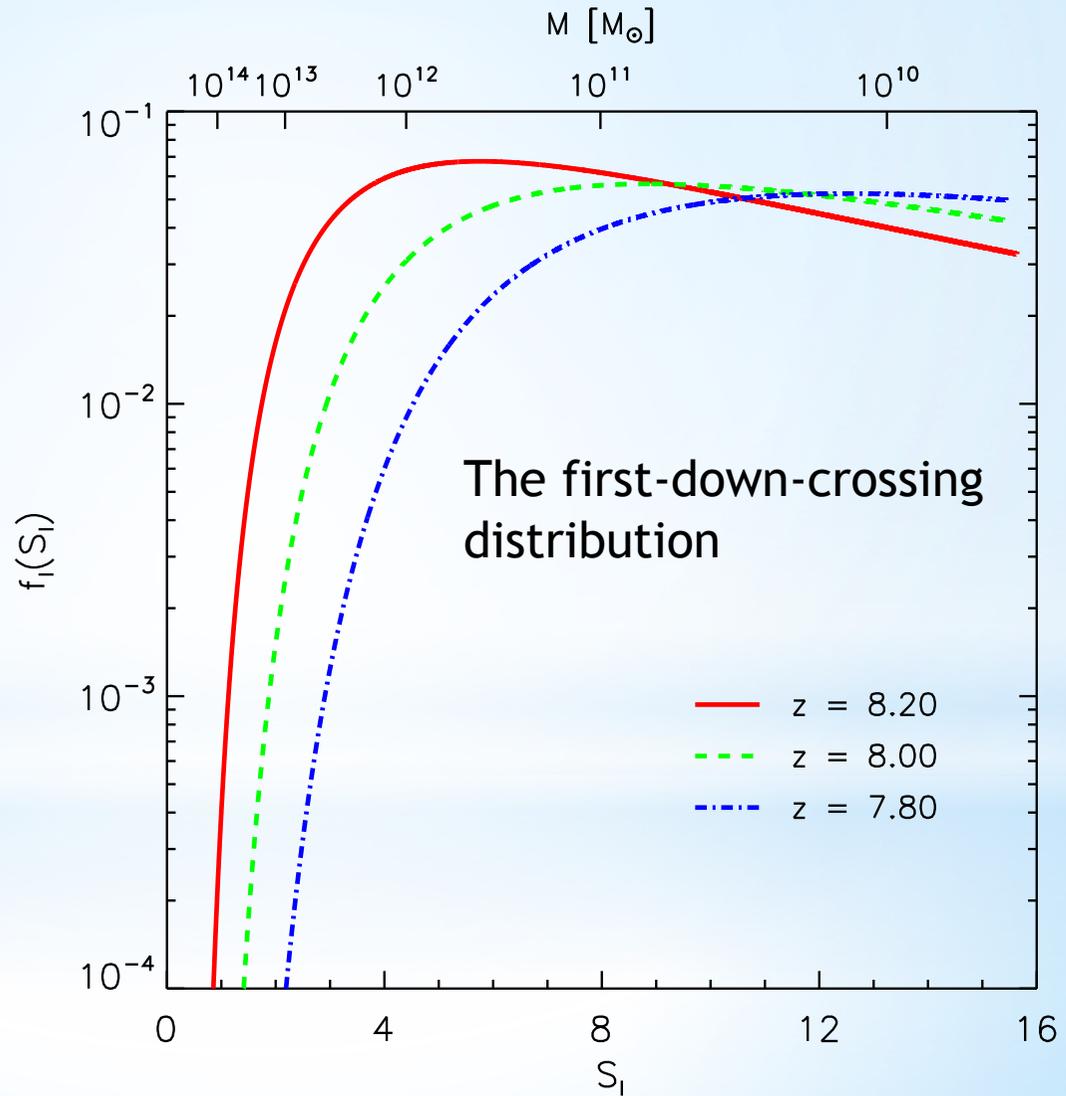
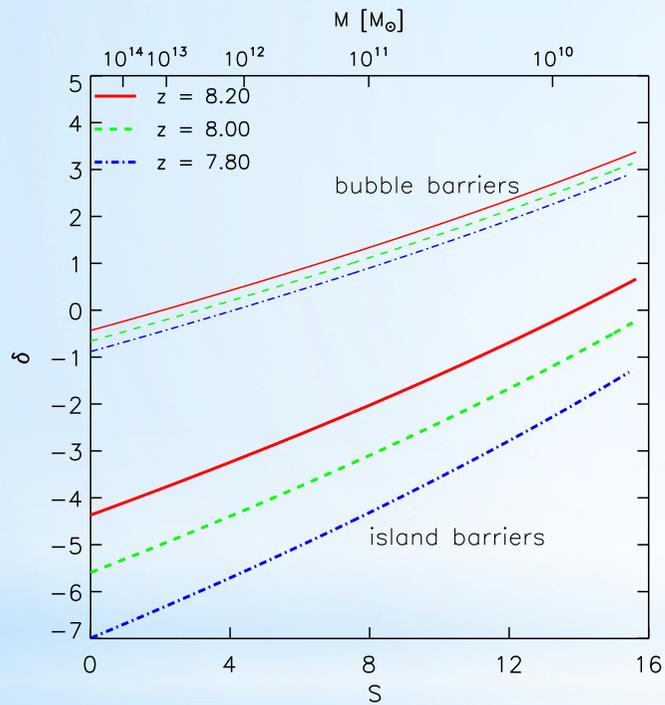
$$N_{\text{back}}/M = n_{\gamma}/\bar{\rho}_{\text{m}}.$$



$$\delta_I(M, z) = \delta_c(z) - \sqrt{2[S_{\max} - S(M)]} \operatorname{erfc}^{-1} [K(z)]$$

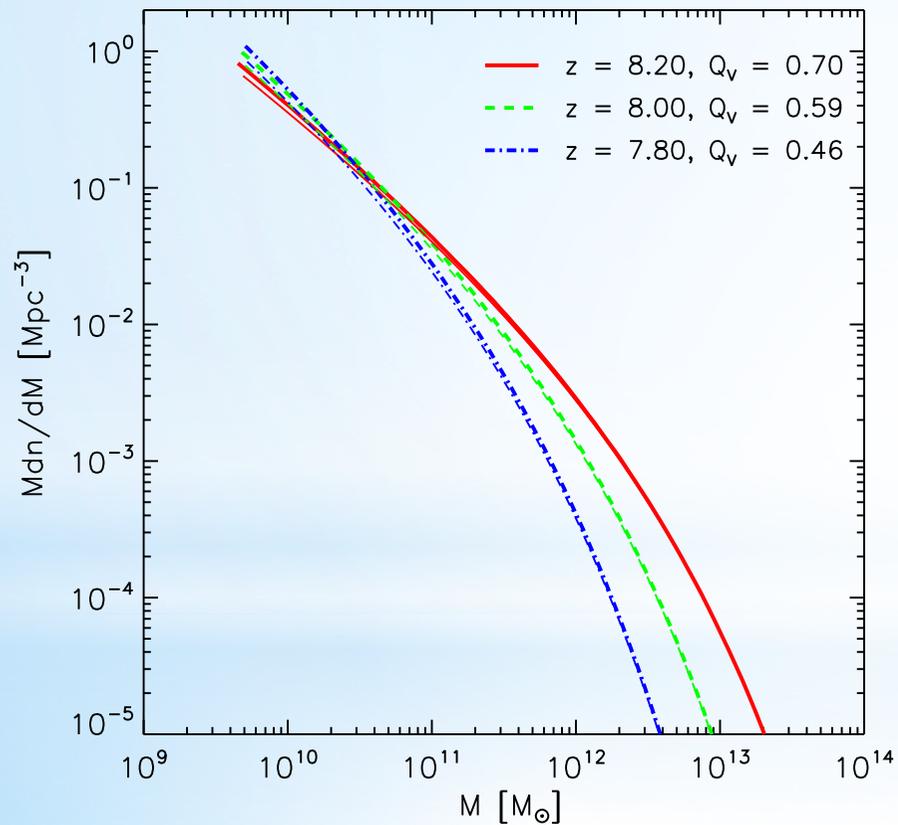


A toy model - island-V

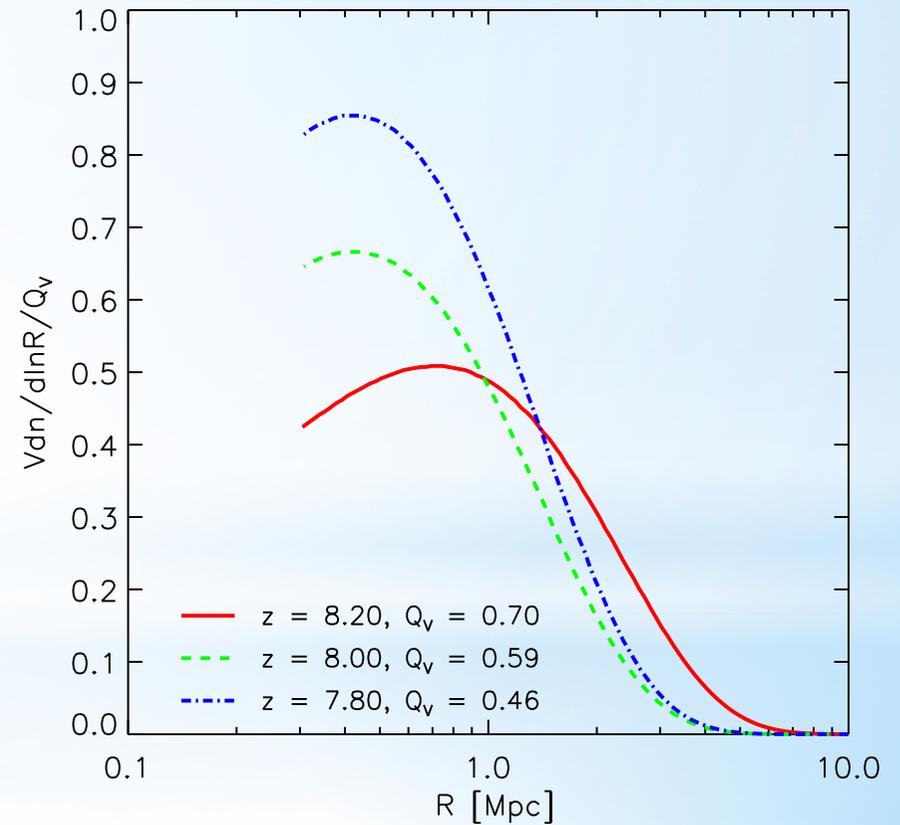


A toy model - island-V model

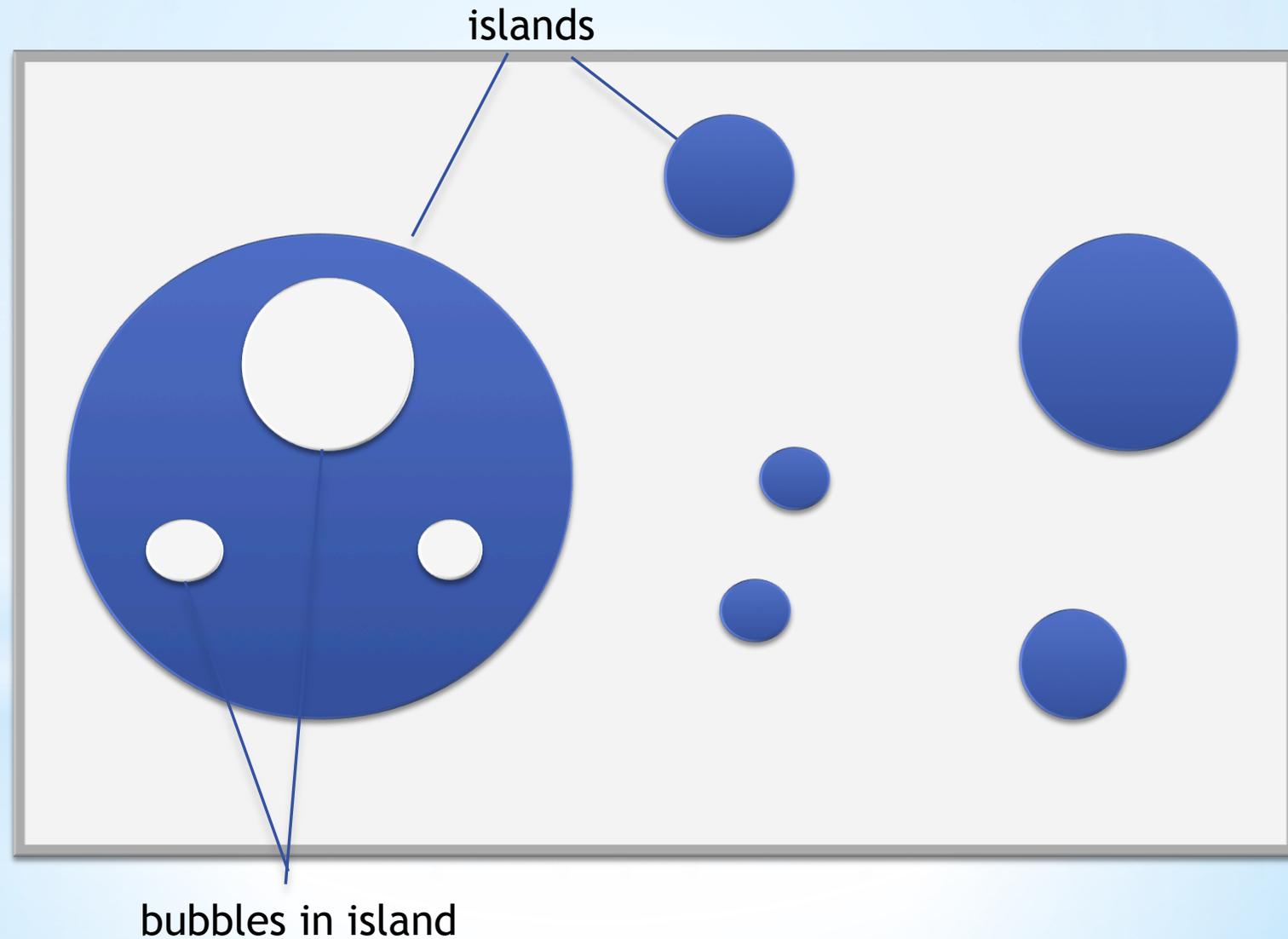
Mass function of islands



Size distribution of islands



Complication: bubbles in island



Modeling the bubbles-in-island effect

* Solving for a two-barrier problem:

1 - The first down-crossing distribution of random walks w.r.t. **island barrier**:

$$f_I(S_I, z)$$

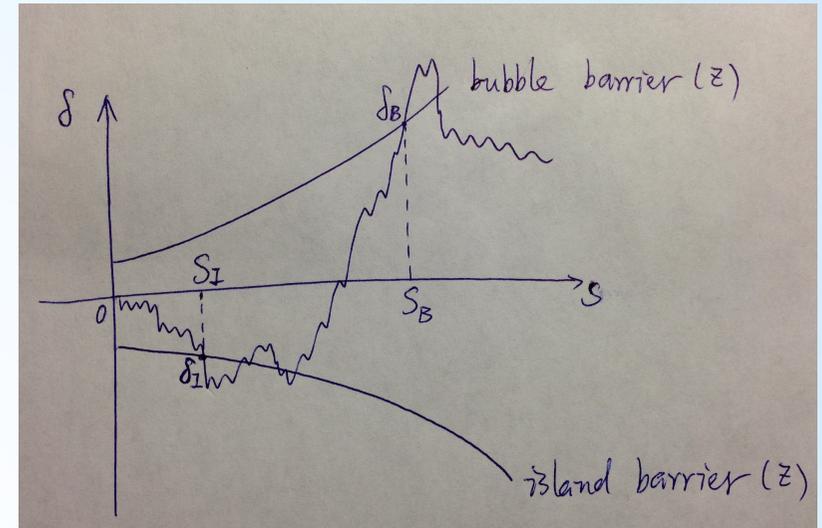
2 - The conditional first up-crossing

distribution w.r.t. **bubble barrier**: $f_B[S_B, \delta_B | S_I, \delta_I]$

* The effective bubble barrier:

$$\delta'_B = \delta_B(S + S_I) - \delta_I(S_I)$$

$$S = S_B - S_I.$$



The bubbles-in-island effect

*The bubbles-in-island fraction:

$$q_B(S_I, \delta_I; z) = \int_{S_I}^{S_{\max}(\xi \cdot M_{\min})} [1 + \delta_I D(z)] f_B[S_B, \delta_B | S_I, \delta_I] dS_B.$$

*The neutral island mass function:

$$\frac{dn}{dM}(M, z) = \frac{dn}{dM_I} \frac{dM_I}{dM} = \frac{\bar{\rho}_{m,0}}{M_I} f_I(S_I, z) \left| \frac{dS_I}{dM_I} \right| \frac{dM_I}{dM}.$$

$$M = M_I(S_I) [1 - q_B(S_I, \delta_I; z)]$$

The ionizing background

- * Considering the effect of *Lyman limit systems* on the mean free path of ionizing photons, the comoving number density of background ionizing photons is

$$n_{\gamma}(z) = \int_z \bar{n}_{\text{H}} \left| \frac{df_{\text{coll}}(z')}{dz'} \right| f_{\star} N_{\gamma/\text{H}} f_{\text{esc}} \exp \left[- \frac{l(z, z')}{\lambda_{\text{mfp}}(z)} \right] dz',$$

- * With the MHR00 model for the volume-weighted density distribution of the IGM (Miralda-Escude et al. 2000),

$$P_{\text{V}}(\Delta) d\Delta = A_0 \exp \left[- \frac{(\Delta^{-2/3} - C_0)^2}{2(2\delta_0/3)^2} \right] \Delta^{-\beta} d\Delta$$

the mean free path of ionizing photons can be written as

$$\lambda_{\text{mfp}} = \frac{\lambda_0}{[1 - F_{\text{V}}(\Delta_{\text{crit}})]^{2/3}},$$

The ionizing background

- * The critical relative density for a clump to self-shield

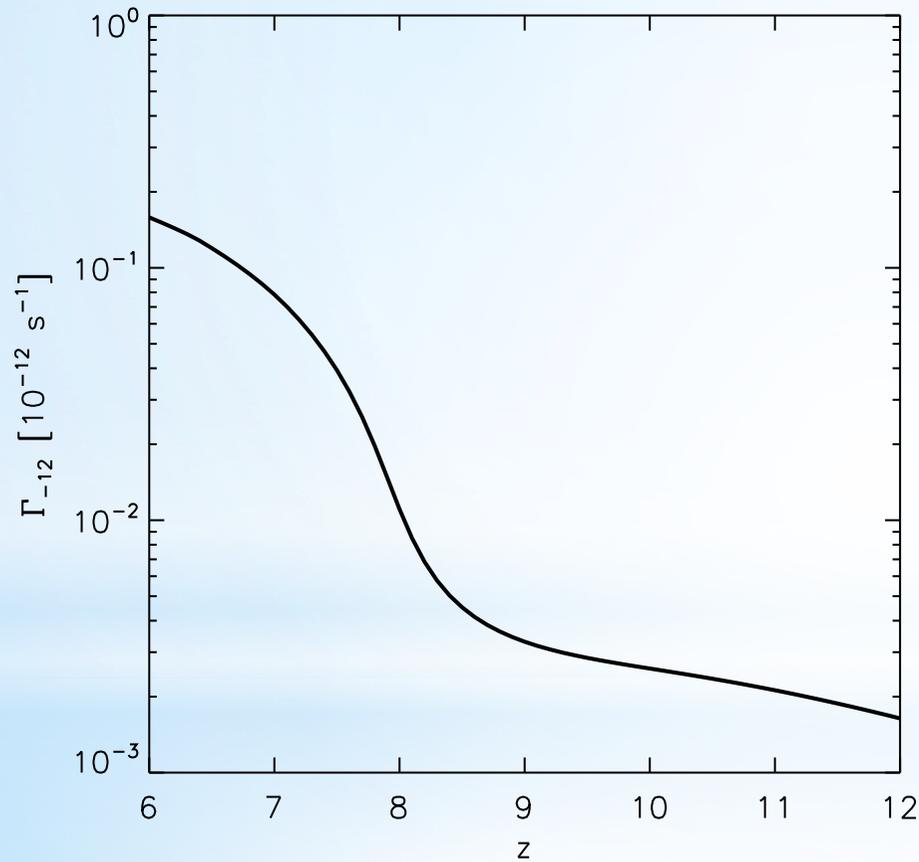
$$\Delta_{\text{crit}} = 36 \Gamma_{-12}^{2/3} T_4^{2/15} \left(\frac{\mu}{0.61} \right)^{1/3} \left(\frac{f_e}{1.08} \right)^{-2/3} \left(\frac{1+z}{8} \right)^{-3}$$

- * The HI photoionization rate Γ_{HI} is related to the total number density of ionizing photons n_γ by

$$\Gamma_{\text{HI}} = \int \frac{dn_\gamma}{d\nu} (1+z)^3 c \sigma_\nu d\nu,$$

- * Scaling the hydrogen photoionization rate to be $\Gamma_{\text{HI}} = 10^{-12.8} \text{ s}^{-1}$ at redshift 6, as suggested by recent measurements from the Ly- α forest (Wyithe & Bolton 2011; Calverley et al. 2011)

The ionizing background



Consistent with our definition of the
“background onset time”

The island-vS model (nearly realistic)

- * We assume that the photons consumed by an island at any instant is proportional to its surface area, then

$$N_{\text{back}} = \int F(z) \Sigma_{\text{I}}(t) dt, \quad F(z) = n_{\gamma}(z) (1+z)^3 c/4.$$

- * For a spherical island,

$$n_{\text{H}}(R)(1 + \bar{n}_{\text{rec}}) 4\pi R^2 (-dR) = F(z) \frac{4\pi R^2}{(1+z)^2} dt,$$

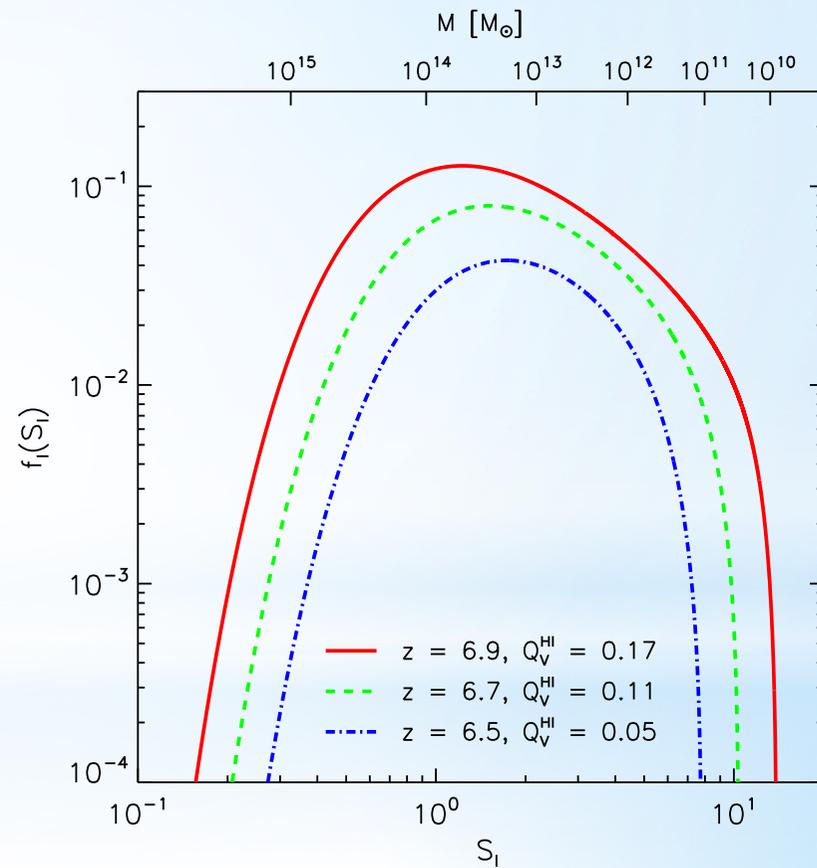
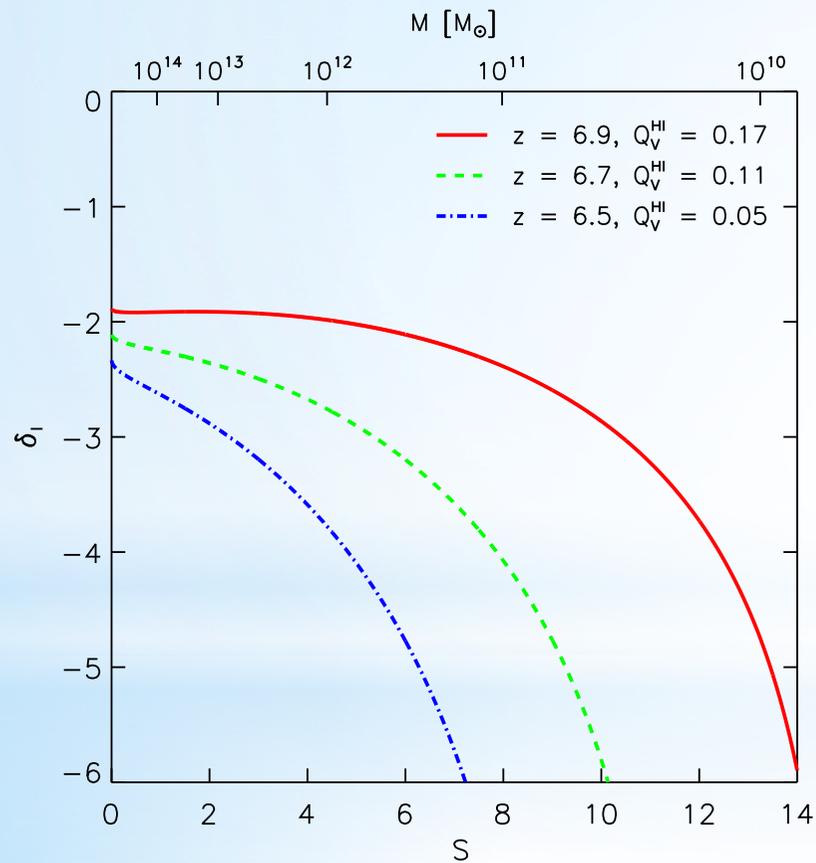
$$\Delta R \equiv R_i - R_f = \int_z^{z_{\text{back}}} \frac{F(z)}{\bar{n}_{\text{H}}(1 + \bar{n}_{\text{rec}})} \frac{dz}{H(z)(1+z)^3},$$

- * The total number of background ionizing photons consumed is

$$N_{\text{back}} = \frac{4\pi}{3} (R_i^3 - R_f^3) \bar{n}_{\text{H}}(1 + \bar{n}_{\text{rec}}),$$

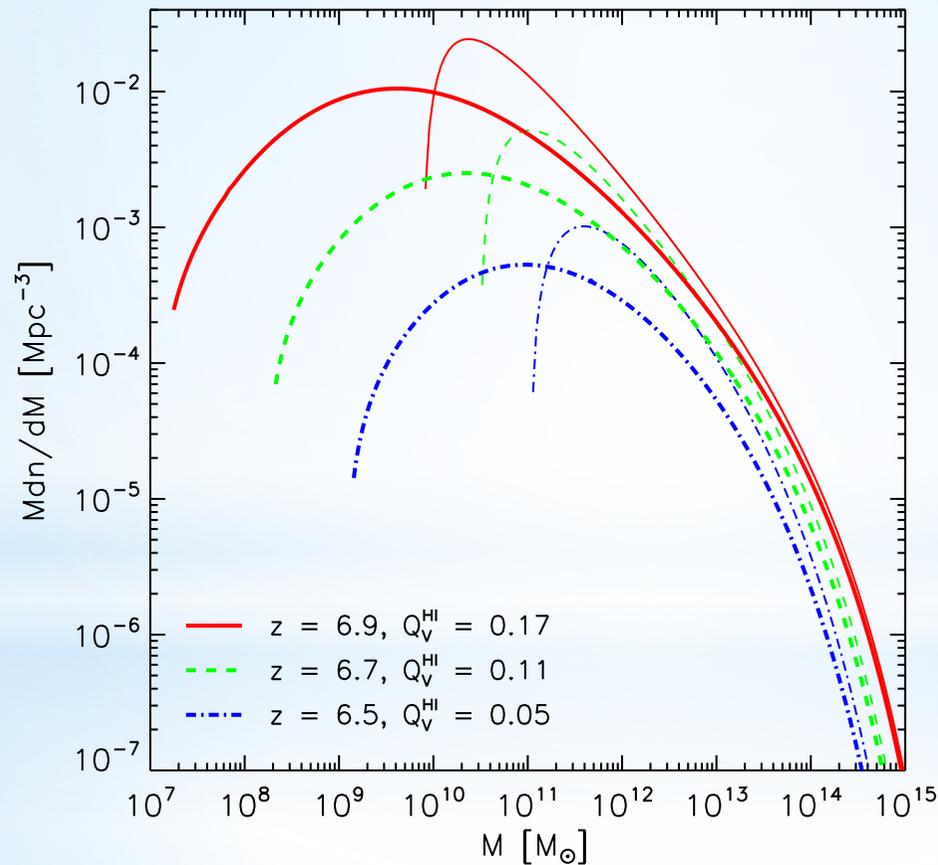
The island- ν S model

- the island barrier and first down-crossing distribution



The island-vS model

- the host island (including bubbles) mass function

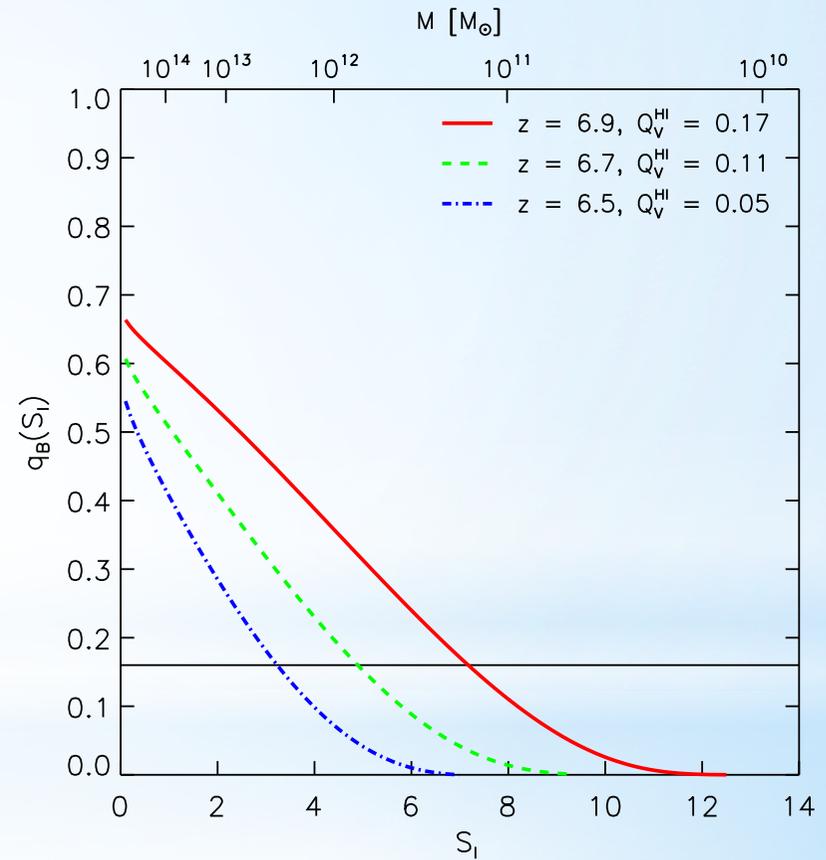
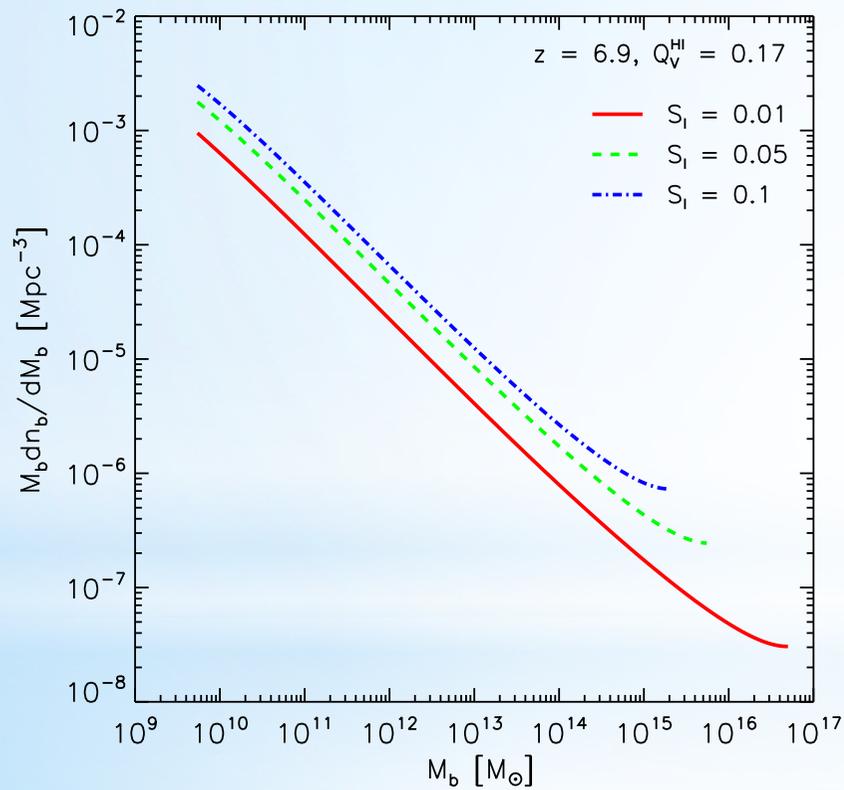


➤ The shrinking hosts

$$\frac{M_f}{M_i} = \left(1 - \frac{\Delta R}{R_i}\right)^3$$

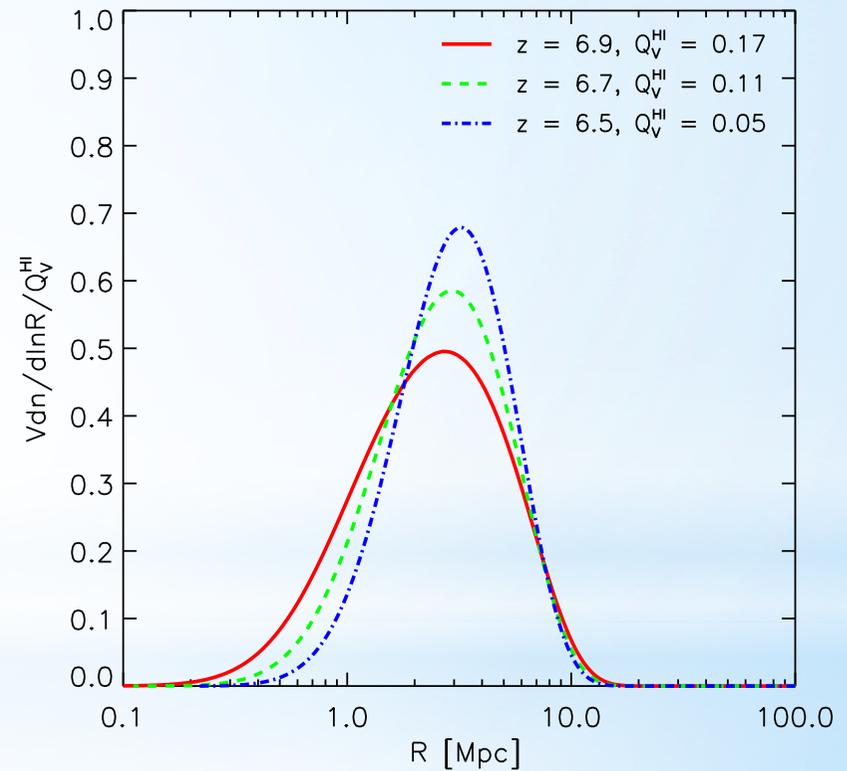
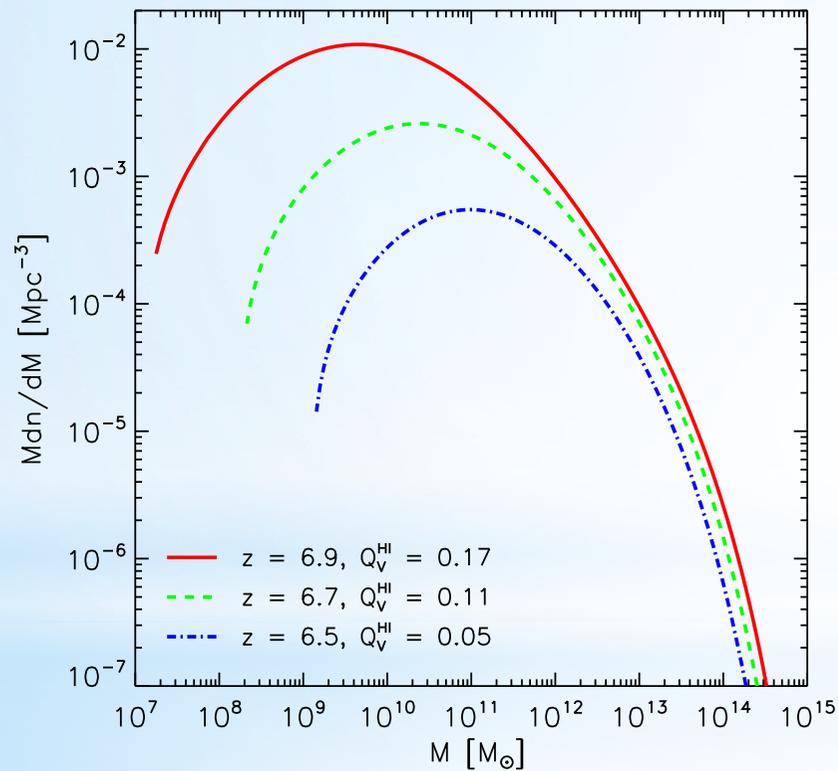
The island-vS model

- the bubbles-in-island



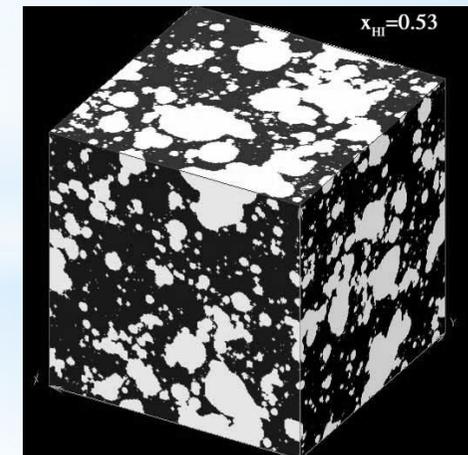
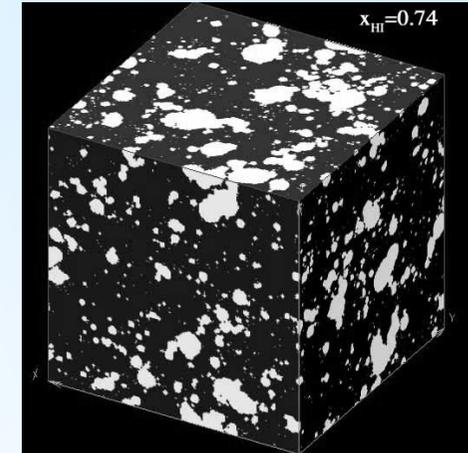
The island-vS model

- the mass function and size distribution



The problem of large bubbles-in-island fraction

- * Host islands \rightarrow overestimate the neutral fraction
- * Neutral island \rightarrow atoll or smaller islands?
- * Difficult to visually identify the host islands
- * Break down of bubble model inside islands
- * Percolation of islands



percolation problem

percolation threshold p_c

* The bubble model regime:

$$z > z_{Bp} \quad (x_{HII} < p_c)$$

* The island model regime:

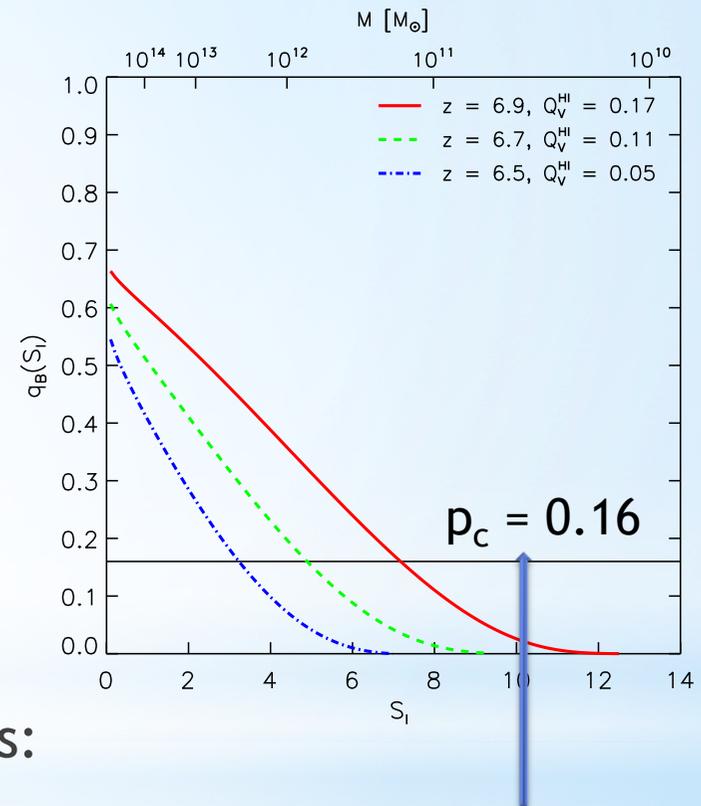
$$z < z_{Ip} \quad (x_{HI} < p_c)$$

* The background onset redshift:

$$z_{Bp} > z_{back} > z_{Ip}$$

* The definition of bona fide neutral islands:

$$q_B < p_c$$



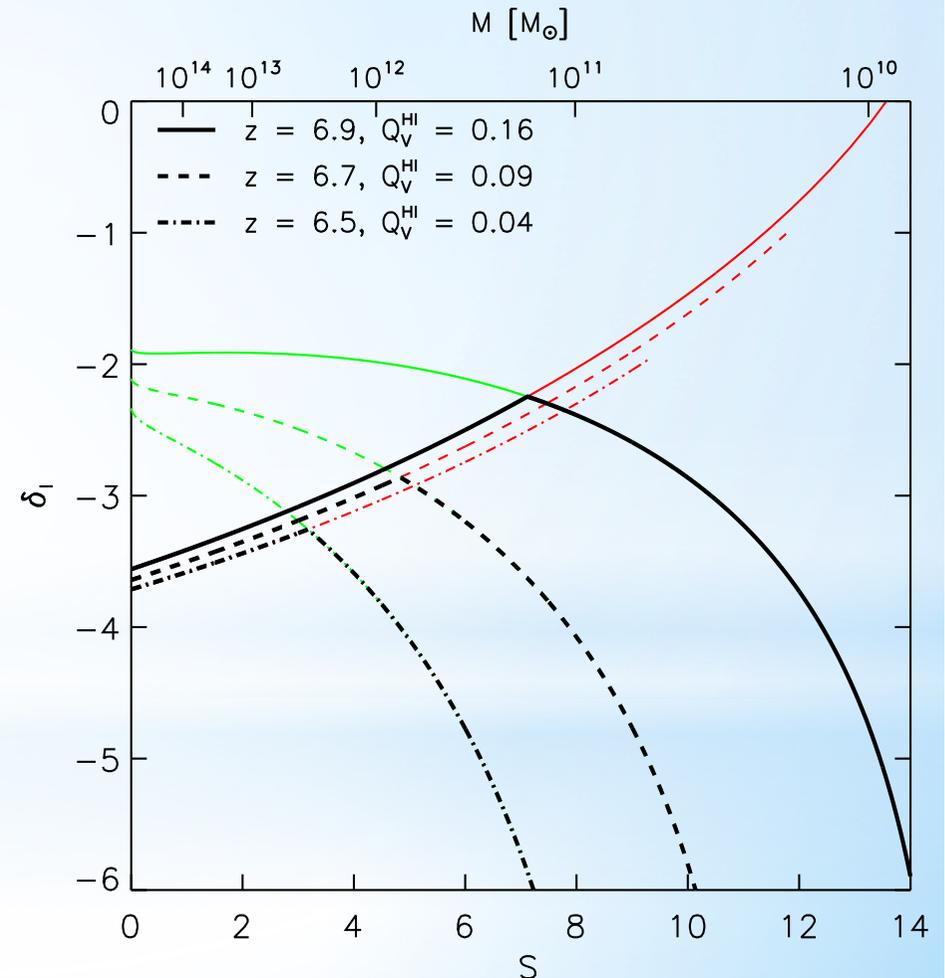
for Gaussian random fields

The percolation criterion:

- * Limit ourselves to the valid (not percolated) case
- * Find bona fide neutral islands
- * The additional barrier is obtained by solving

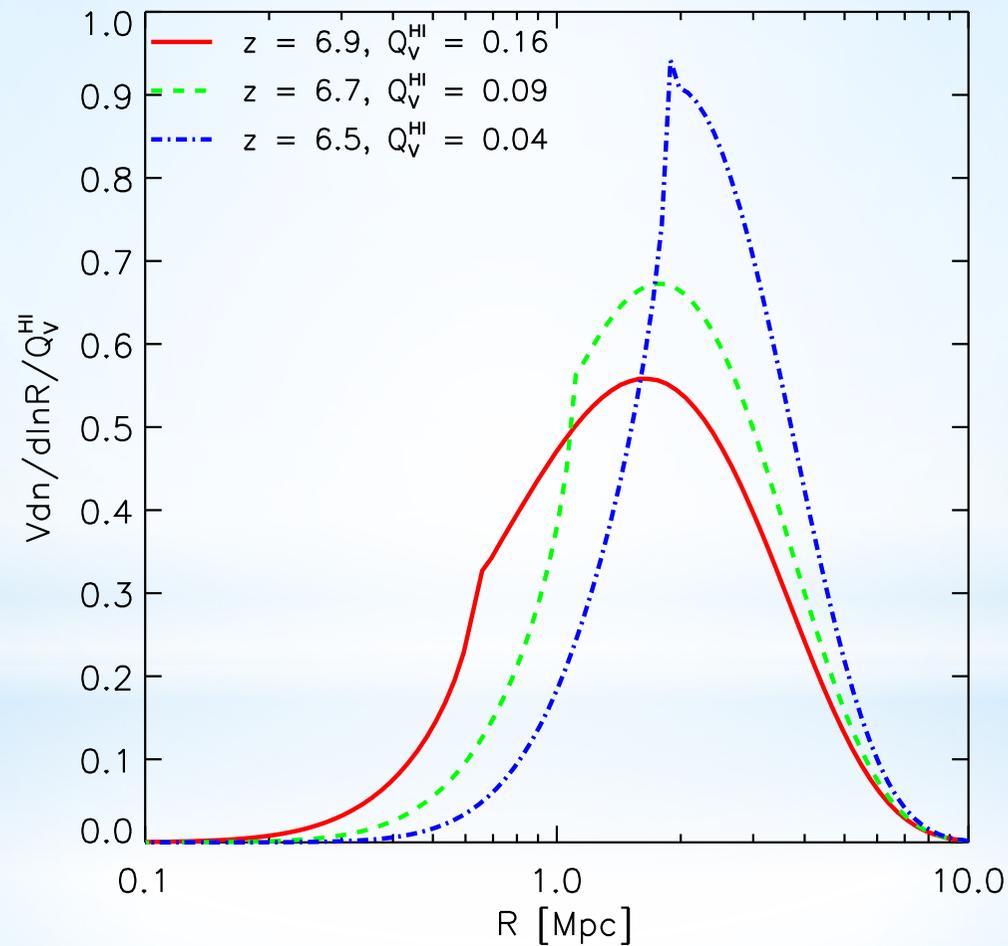
$$q_B(S_I, \delta_I; z) < p_c$$

- * $p_c = 0.16$ for Gaussian random fields



Results

- the size distribution with p_c cutoff

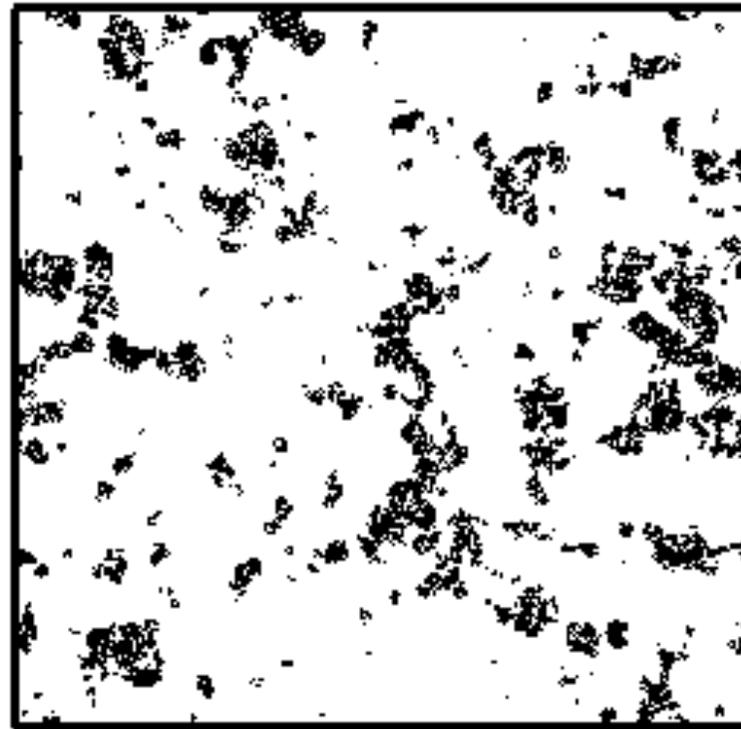


Summary

An analytical model of neutral islands during the late EoR based on the excursion set theory, to help understand reionization process

- * An island barrier on the density contrast for the islands to remain neutral, with the inclusion of an ionizing background.
- * An island was identified when the random walk first-down-crosses the island barrier.
- * We took into account the effect of bubbles-in-island by computing the conditional first up-crossing distribution.
- * An semi-empirical way to determine the intensity of the ionizing background self-consistently.
- * A percolation criterion was applied to find bona fide neutral islands
- * The size distribution of neutral islands shows a peak indicating a characteristic scale of the islands, and it does not change much with redshift.

THANK YOU!



512 Mpc, 1024^3